
Cycloids and limaçons in the turtle graphics

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Abstract

In my understanding the main purpose of education in science is to help our students with deeper understanding of the main ideas of mathematics and physics and teach them to find the proper tools and methods of discovering the rules, and as a result to encourage them to study on their own to continue the so-called lifelong learning process.

The ready demonstration programs prepared by the teacher or found in the internet are applied to check the way the results depend on the data initially introduced. If the student writes a demonstration program himself/ herself/ they get a chance of deeper understanding of the problem. One approach does not exclude the other or rather they are complementary.

We should study the problem from different points of view; to show different approaches to the same problem. The purpose of the paper is to give a proper tool rather than to give ready answers.

In this paper two points of view are contrasted and compared: the intrinsic (pen-coordinate system) and the extrinsic one (page coordinate system) and also Cartesian and polar plots of the sine family function. Uniform circular motion is a source of a sine wave, circular motion combined with translation gives regular cycloid and a combination of two circular motions produce Lissajous curves and when one circle rolls upon another circle the cycloids are created. The rotational motion is convenient to be realized in intrinsic way, when it is combined with translation or another rotation it is convenient to relate it to the extrinsic coordinate system but it is not necessary. Intrinsic realization of combined motions slows down the process of drawing. Then we can simulate the parallel processes using many turtles.

The following two articles have inspired me to do all this trials: (Armon, 1997) and (Farcas, 2003). Another reason for writing this work is my experience connected with quantum chemistry course when we are trying to imagine what the orbitals looks like. The source of our difficulties is the fact that the students have seen polar plots of the sine family function never before.

I start with the source definition of the sine function. Then I show the simplest way to create the Lissajous figures. Next I demonstrate how the circular motion generates a Cartesian plot and next the polar plot of the sine family functions (rhodonea, limaçons). (It was like discovering the original simplicity of the problem which we have already learnt to see as complicated.) At the next step the superposition of two waves is graphically presented in both coordinate systems. I also present the procedure for generation of a family of cycloidal curves (in a wide meaning) – hypo- and epi-cycloids are the special cases of this general procedure. Then I propose to investigate the Cartesian and polar plots of cycloidally modulated waves and also cycloidally modulated Lissajous figures. This paper presents only a few curves from a huge variety and number of possible ones that can be generated using the procedures proposed. At the end I mention the alternative way of creating polar plots and a beautiful way of creating cycloids and other curves defined by intrinsic curvature proposed by Armon (Armon, 1997).

I intend to show that Logo is convenient and fruitful tool for investigation of the Cartesian plots and polar plots of the curves from the families of limaçons, rhodoneas and cycloids created in the intrinsic style.

Keywords

circular motion, harmonic oscillator model, complex harmonic motion, Lissajous curves (figures), polar coordinates, sine function, cycloid, limaçon

Introduction – the definition of the sine function

The harmonic oscillator is the most powerful and most widely used single model in all of physical science. It is the basis of much of our understanding of the behaviour of molecules and electromagnetic radiation. In the harmonic oscillator model the sine function describes displacement, while the cosine – velocity, as a function of time.

The sine function and every superposition (linear combination) of different sinusoidal waves (Fourier series) are the solutions of the classical wave equation. The sine function is an important component of the solutions of quantum-mechanical wave equation (orbitals). What is the source definition of the sine function? Probably when hearing “the sine function” most people see a Cartesian plot of this function, a sinusoidal wave. But we know, that there is not one and only way to represent this function graphically. The Cartesian plot is one of many possible conventions. The source definition of the sine function is (Weisstein, 2006):

The sine function is the vertical coordinate of the arc endpoint of the unit circle rotating uniformly counter clockwise.

The circular motion is assumed to be at a constant speed (angular speed) or alternatively with a constant frequency measured in revolutions per unit of time. It means that the angle or time is the variable. The sine curve is created when the y coordinate of the constant circular motion becomes the y coordinate of the Cartesian plot, whereas the x coordinate originates from a translation along the x axis at a constant speed related (in time) to the speed of the circular motion. The relation is established by the frequency of the circular motion, i.e. by the number of revolutions made during translation in the x direction over a distance of two diameters of the circle.

We need four turtles with the same initial position and different shapes and pen colours to draw a sine curve. The first turtle (t4) draws a circle and transfers his y coordinate to another turtle (t3), the third one (t2) goes along the x axis (i.e. the propagation direction of the wave) with a proper constant step (hx) and the last one (t1) takes the y coordinate from t4 or t3 and x coordinate from t2 and draws a sine curve as a result. Turtles t2 and t3 are redundant for drawing sine curve: they only transfer coordinates between the turtle performing the circular motion (t4) and the turtle performing the sine curve (t1), but they visualize the whole process very well.

It is convenient to assume that the circle is performed by the statement:

```
repeat 360 [fd :s rt 1]
```

where :s parameter is the arc length step corresponding to Δs and $\Delta \phi$ is constant and equal to 1. Therefore $1/:s$ is a measure of the intrinsic curvature of the circle and also the angular speed of the point moving over a circular orbit. Let the sine function be defined as:

$$y = a \sin (n x + p)$$

where a is the amplitude, n is the frequency and p is the phase. If $n = 1$, the distance of two diagonals of the circle must be completed during one revolution of a circle, for $n = 2$ – during two revolutions of a circle etc. The amplitude a is the radius of the circle. Let one step in translation in x direction be hx. Phase p is the initial position of the turtle drawing a circle (circular motion at a constant speed) measured in degrees. Phase 90 means that $y = a \cos (n x)$.

We can choose a, n, and p as an input for the procedure and calculate s and hx or we can start with s, n and p and calculate a and hx. The sine function is described by three independent variables. The procedure sinecurve1 creates a sine curve with four turtles, procedure sinecurve2 – with two turtles. What will happen if we change rt into lt in these two procedures?

```
to sinecurve1 :a :n :p
; y = a sin (n x + p)
make "s :a * 3.14 / 180 make "hx 2 * :s / :n / 3.14
```

```

;initial positions for turtles
cs ask [t1 t2 t3 t4][pu setpos [-300 0] pd] ask "t4 [repeat :p [fd :s rt 1]]
ask "t1 [pu setycor ask "t4 [ycor] pd]

repeat 360 * :n [ask [t4] [fd :s rt 1] ask [t1 t2] [setxcor xcor + :hx]
ask [t1 t3] [setycor ask "t4 [ycor]] wait 10]

end

? sinecurve1 100 2 90
? ask [t1 t2 t3 t4][stamp]

```

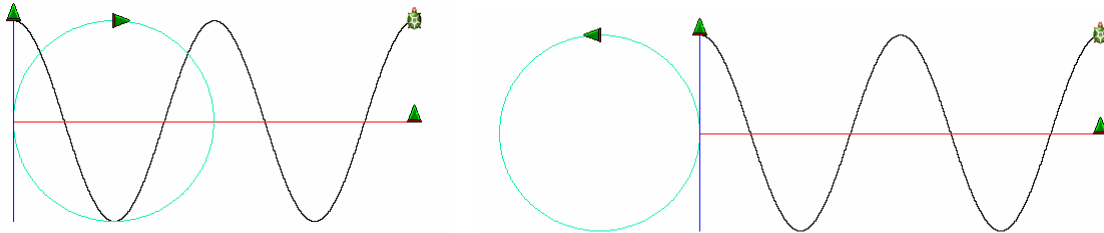


Fig.1 The cosine function with *rt* (left) and *lt* (right) created by procedure *sinecurve1*

In the procedure *sinecurve2* the turtles *t2* and *t3* are unemployed and the bolded part of the procedure *sinecurve1* is replaced by:

```

repeat 360 * :n [ask [t4] [fd :s rt 1] ask [t1 ] [setxcor xcor + :hx setycor ask "t4 [ycor]]
wait 10]

? sinecurve2 100 2 90
? ask [t1 t4][stamp]

```

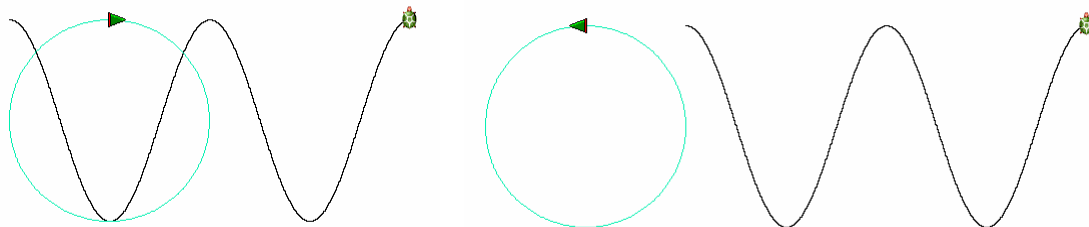


Fig.2 The cosine function with *rt* (left) and *lt* (right) created by procedure *sinecurve2*

Lissajous curves in the turtle graphics.

This family of curves was investigated by Nathaniel Bowditch in 1815, and later in more detail by Jules Antoine Lissajous in 1857.

Jules Antoine Lissajous (1822-1880) was a French mathematician and physicist. He was interested in waves and developed an optical method for studying vibrations. Lissajous curves have applications in physics, astronomy, and other sciences.

Some of these figures, and geometrical methods of constructing them, have been discovered independently, e.g. the Lemniscate of Gerono (eight curve) (Xah Lee, 2004).

The Lissajous figures are created by the system of parametric equations which describes two perpendicular harmonic vibrations:

$$\begin{cases} x = r_1 \sin(n_1 t + p) \\ y = r_2 \sin(n_2 t) \end{cases}$$

Do we need the sinusoid to generate the Lissajous curves, or could only two circular motions create these figures? If the latter was possible, it would be the simplest way to create the Lissajous figures.

The time variable t changes from the moment when the process starts to the moment when the process ends (after n_1 revolutions along first circle and n_2 revolutions along the second circle, circular motions are simultaneous). The turtle drawing the Lissajous curve takes the x coordinate from one turtle moving along the green circle and y coordinate from the turtle drawing the second, blue, circle. We can use three turtles or five turtles. In the last case these additional two turtles transfer the coordinates between those drawing the circles and the one drawing the Lissajous figure. We can also use 3 turtles and make two of them invisible: in that case we will see only one turtle drawing the Lissajous curve. The parameters of the procedure (data) could be the steps for circular motion (Δs_1 and Δs_2) or the radii (amplitudes r_1 and r_2), phase (p) and frequencies (n_1 and n_2). After some trials we will see that the shape of the L figures depends on the ratio of the frequencies of the two perpendicular waves. Dissimilar shapes can be selected by dividing the number of repetitions by the greatest common divisor of the two frequencies or by choosing only these values of frequencies whose greatest common divisor is 1.

The procedures are given for rt case only. The turtles must be created with proper attributes at the beginning.

to turtles

```
new "Turtle [penColour "green4] ask "t2 [setshape loadImage "|Triangle Turtle.lgf]
new "Turtle [penColour "blue] ask "t3 [setshape loadImage "|Triangle Turtleb.lgf]
new "Turtle [penColour "green4] ask "t4 [setshape loadImage "|Triangle Turtle.lgf]
new "Turtle [penColour "paleRed penwidth 2] ask "t5 [setshape loadImage "|Turtle.lgf]
ask "t1 [setshape loadImage "|Triangle Turtleb.lgf] setpencolour "blue]
end
```

```
to GCD :a :b
```

```
  while [:b <> 0] [let "r mod :a :b let "a :b let "b :r]
  op :a
end
```

```
to hop :dx :dy
```

```
  pu rt 90 fd :dx lt 90 fd :dy pd
end
```

```
to Lissajous :s1 :s2 :p :n1 :n2
```

```
cs
;amplitudes
make "x 180 / 3.14
make "r1 :s1 * :x make "r2 :s2 * :x
;initial position for turtles
ask "t3 [hop -:r1 0]
ask "t4 [hop 0 :r2 rt 90 pu repeat :p
  [fd :s2 rt 1] pd ]
ask "t5 [pu setxcor ask "t4 [xcor]
  setycor ask "t3 [ycor] pd]

repeat 360 * :n1 * :n2 / GCD :n1 :n2
  [ask [t3] [fd :s1 / :n2 rt 1 / :n2]
  ask [t1 t5] [setycor ask "t3 [ycor]]
  ask [t4] [fd :s2 / :n1 rt 1 / :n1]
  ask [t2 t5] [setxcor ask "t4 [xcor]]
  wait 10]

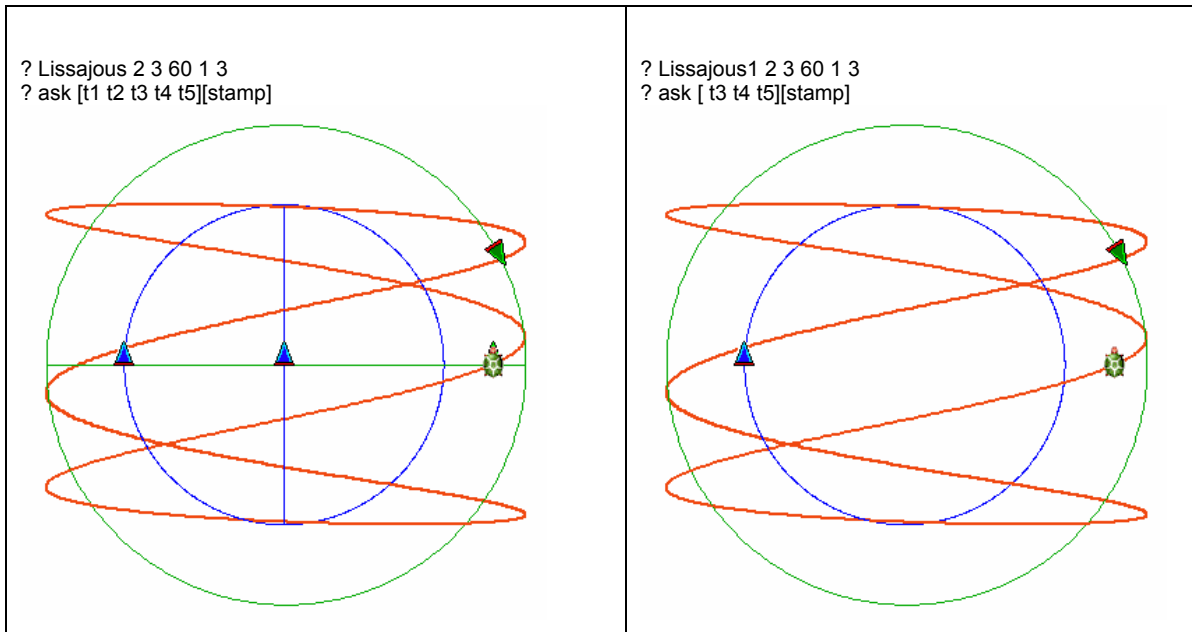
end
```

```
to Lissajous1 :s1 :s2 :p :n1 :n2
```

```
cs
;without t1 and t2
;amplitudes
make "x 180 / 3.14
make "r1 :s1 * :x make "r2 :s2 * :x
;initial position for turtles
ask "t3 [hop -:r1 0]
ask "t4 [hop 0 :r2 rt 90 pu repeat :p
  [fd :s2 rt 1] pd ]
ask "t5 [pu setxcor ask "t4 [xcor]
  setycor ask "t3 [ycor] pd]

repeat 360 * :n1 * :n2 / GCD :n1 :n2
  [ask [t3] [fd :s1 / :n2 rt 1 / :n2]
  ask [t4] [fd :s2 / :n1 rt 1 / :n1]
  ask [t5] [setxcor ask "t4 [xcor]
  setycor ask "t3 [ycor]]
  wait 10]

end
```



In the following demo the statement “/ GCD :n1 :n2” in the Lissajous procedure may be removed.

to demoLissajous

```
for "s1 [2 3] [for "n1 [1 5][for "n2 (se :n1 5) [for "p [0 360 15] [if GCD :n1 :n2 = 1
[(print [phase=] :p) (print [amplitude1=] :s1) (print [amplitude2=] 3)
(print [frequency1=] :n1) (print [frequency2=] :n2)
Lissajous :s1 3 :p :n1 :n2] wait 100] wait 1000]]]
end
```

The bolded part of the Lissajous procedure could have another different shape – it gives the same result but works quicker and less accurate.

```
repeat 360 [ask [t3] [dot fd :s1 * :n1 rt :n1] ask [t4] [dot fd :s2 * :n2 rt :n2]
ask [t5] [setxcor ask "t4 [xcor] setycor ask "t3 [ycor] dot]]
```

Polar coordinates and polar plot of the sine functions

What determines the choice of the coordinate system in a given situation? Why the Cartesian coordinates are not used to identify the position of our town on the globe? For the same reason we do not use the Cartesian coordinates to determine the position of an electron with respect to the atomic nucleus. The reason is symmetry. When the coordinate system suits the symmetry of the object under consideration, the equations describing it become simpler, and the calculations easier. For example: the equation of a circle of radius r centred at the pole is $r^2 = x^2 + y^2$ in the Cartesian coordinates, while in the polar coordinates it is: $r = const$. I suspect that in everyday life we use polar coordinates and their three dimensional counterpart, i.e. spherical coordinates (in geography), more frequently than the Cartesian coordinates. However, we usually do not know how simple mathematical functions look in the polar coordinates. What benefit could come from drawing them in polar coordinates? Could we understand better for example the shapes of the orbitals (one electron wave functions which are the solutions of time independent Schrödinger equation) in chemistry? Let us investigate only one family of sine functions, namely $r = \sin(n\varphi)$. Is there anything the students/pupils can discover in this area? I ask my students to describe in a laboratory report their findings they found particularly interesting. One of the students answered: “Honestly speaking, every subsequent function was a huge discovery, great news and a great riddle for me.” His answer encouraged me to share my didactic experience with you.

For the definition of the polar coordinates see for example (Weisstein, 2002).

R is the radial distance from the origin (initial position of the turtle), φ is defined as the counter clockwise angle from the x axis, but in Logo it will be convenient to choose φ as the clockwise angle from the N-S axis (by the way: it is a good exercise to see what is the difference between the different possibilities of choosing the reference axis and the direction of counting the angle).

We offer a job to the fifth turtle (besides four introduced in the Introduction) who for subsequent values of angle φ (from 0 to 360 with the step 1) draws a line (vector) of length equal to the value of the sine function for this particular value of variable, namely equal to $\sin \varphi$. The value of $\sin \varphi$ is equal to the value of y coordinate of the turtle rounding along the circle (and turtle oscillating along the y axis). Besides of the usual "mathematical convention" we can try also the frequently used convention of drawing the radii (vectors r) corresponding to the negative values of the function as positive and in different colour. Let us call it the "two-colour convention" (unfortunately I use two colours in every convention).

to turtles

```
repeat 4 [new "Turtle []]
ask [t2 t3 t4] [setshape loadImage "|Triangle Turtle.lgf]
ask "t1 [setPW 2]
ask "t5 [setPW 2 setHomestate [[200 0]0] setshape loadImage "|Turtle.lgf]
end
```

Below the procedure sinepolarplot which is a good tool to demonstrate the shapes of the sine family functions in the polar coordinates ("mathematical convention").

```
to sinepolarplot :a :n :p
; y = a sin (n x + p)
let"s :a * 3.14 / 180 let "hx 2 * :s / :n / 3.14
; initial positions for turtles
cs ask [t1 t2 t3 t4][pu setpos [-300 0]pd] ask "t4 [repeat :p [fd :s rt 1]]
ask "t1 [pu setycor ask "t4 [ycor] pd] ask [t1 t5][setPW 2 pu]

repeat 360 * :n [let "y ask "t4 [ycor] ask [t4] [fd :s rt 1] ask [t1 t2] [setxcor xcor + :hx]
ask [t1 t3] [setycor :y] ask [t1] [ifelse :y < 0 [setPC 4] [setPC 2] dot]
ask [t5] [ifelse :y < 0 [setPC 4] [setPC 2] fd :y dot bk :y rt 1 / :n] wait 50]

end
```

? sinepolarplot 90 2 0

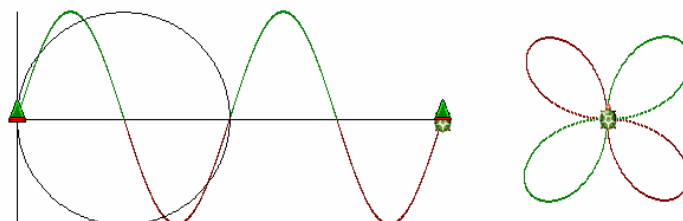


Fig. 3. The Cartesian plot of the function $y = \sin 2x$ and the polar plot of the function $r = \sin 2 \varphi$

On the Fig. 3 is one example of rhodonea (Wassenaar, 2005). As before, we can remove the redundant turtles $t2$ and $t3$, as well as hide the motion of turtles $t4$ and $t1$ if we would like to see the polar plot only. To obtain the functions from the limaçon (Weistein, 2003) family we must only add the constant value to the $ycor$ in the procedure sinepolarplot (Fig. 4 is the example).

The example result for fractional n and enlarged number of repetitions is shown on the Fig.5.

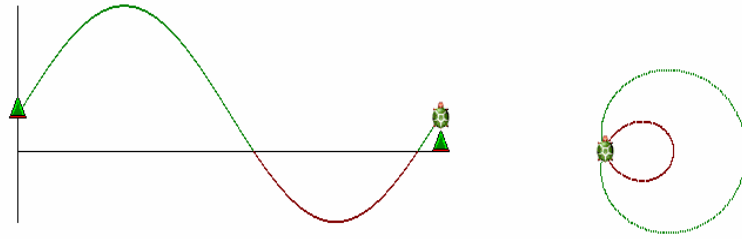


Fig. 4 The Cartesian plot of the function $y = 1/3 + \sin x$ and the polar plot of the function $r = 1/3 + \sin \phi$

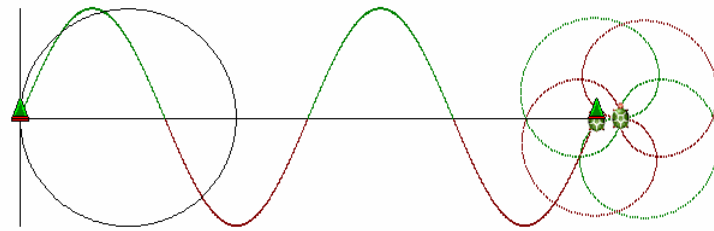


Fig. 5 The Cartesian plot of the function $y = \sin 2/3x$ and the polar plot of the function $r = \sin 2/3\phi$

Program startij demonstrates the limaçon (Wassenaar, 2004) family functions $r = a + \sin(i/j * \phi)$ and shows how the shapes depend on the value of a for a given small integer values of i and j . The positive values are in red, negative in blue, the circle of radius a with black.

```

to sinpij :a :i :j
  cs repeat 360 * :i * :j / GCD :i :j [let "y 100 * (sin :i / :j * (repc - 1)) fd :a + :y
    ifelse :y < 0 [ setpc 1 ] [setpc 12 ] setpw 3 dot bk :y setpc 0 setpw 2 dot bk :a rt 1]
end

to startij
  pu ht
  for "i [1 5][ for "j [1 5][if GCD :i :j = 1 [(pr :i :j) for "a [100 0 -5] [sinpij :a :i :j wait 10] wait 1000]
    for "a [0 -100 -5] [sinpij :a :i :j wait 10] wait 1000]]
end
    
```

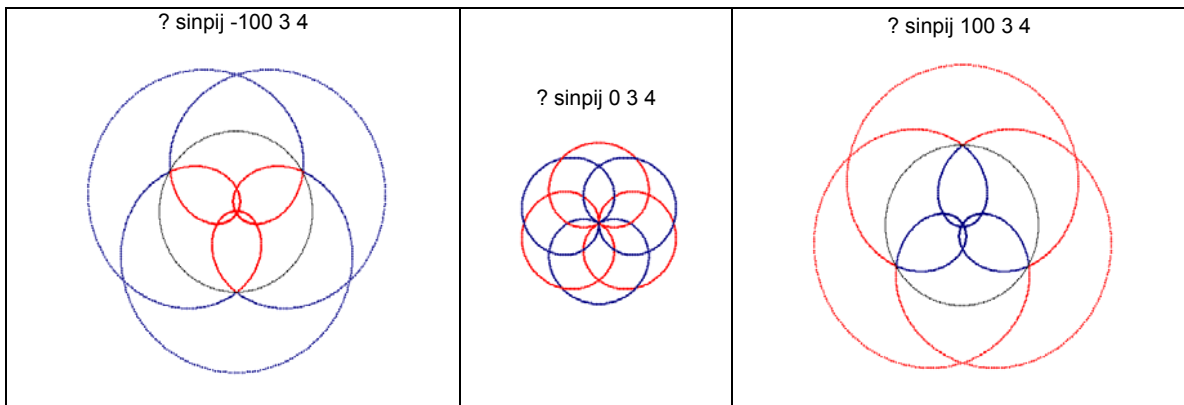


Fig. 6. The polar plots of the functions $r = -1 + \sin 3/4 \phi$, $r = \sin 3/4 \phi$ and $r = 1 + \sin 3/4 \phi$.

Superposition of waves

Now we are ready to demonstrate the Cartesian and polar superposition (interference, beat) of any two waves, each of them characterized by three parameters: amplitude, frequency and phase. We could offer a job for 12 turtles: t4 and t6 are making circular motions, t3 and t9 demonstrates one-dimensional (y direction) harmonic motions, t2 and t8 are making translation in x direction, t1 and t7 create Cartesian plots, t5 and t10 – polar plots and t11 and t12 – Cartesian and polar sums of two given waves. For clarity we can make some of the plots invisible as well as we can hide some of the turtles to show step by step how the superposition of two waves is created and to compare clearly the components and the sum in the Cartesian and polar coordinates. We can also compare the polar plots in the “mathematic” and the “two-colour” conventions.

It is a certain inconsistency to avoid, but only in the Cartesian coordinates, not in the polar ones, when the amplitudes are not the same: one could have the impression that the wave of a small amplitude propagates with a lower velocity but it is a wrong conclusion (see Fig 10, the Cartesian components and the polar sum). We can easily improve the procedure below by scaling hx value by the values of two amplitudes; hx1 ought to be of the same value as hx2.

? sinepolarsumdot 90 45 3 6 0 90

? ask all [stamp]

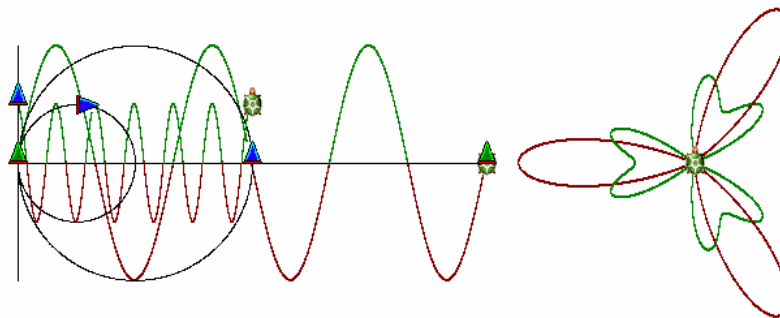


Fig. 7. The Cartesian components and the polar sum of two waves of different amplitudes

Below is one of many possible procedures, sinepolarsumdot:

```
to sinepolarsumdot3 :a1 :a2 :n1 :n2 :p1 :p2
; y1 = a1 sin (n1 x + p1), y2 = a2 sin (n2 x + p2)
let"s1 :a1 * 3.14 / 180 let"s2 :a2 * 3.14 / 180
let "hx1 2 * :s1 / (:n1 * :n2 * 3.14)
let "hx2 2 * :s2 / (:n2 * :n1 * 3.14)
ifelse :hx1 > :hx2 [let "hx :hx1][let "hx :hx2]
; nitial positions for turtles
cs ask [t1 t2 t3 t4 t6 t7 t8 t9 t11][pu setpos [-300 0]pd] ask [t11 t12][st pu]
ask [t4 t6 t8 t9][ht pu] ask [t3 t2][ht] ask "t4 [repeat :p1 * :n2 [fd :s1 / :n2 rt 1 / :n2]]
ask "t6 [repeat :p2 * :n1 [fd :s2 / :n1 rt 1 / :n1]] ask "t1 [pu setycor ask "t4 [ycor] pd]
ask "t7 [pu setycor ask "t6 [ycor] pd] ask [t1 t5 t7 t10][ht pu]

repeat 360 * :n1 * :n2 [let "y1 ask "t4 [ycor] let "y2 ask "t6 [ycor] let "y :y1 + :y2
ask [t4] [fd :s1 / :n2 rt 1 / :n2] ask [t6] [fd :s2 / :n1 rt 1 / :n1]
ask [t1 t2] [setxcor xcor + :hx1] ask [t1 t3] [setycor :y1]
ask [t7 t8] [setxcor xcor + :hx2] ask [t7 t9] [setycor :y2]
ask [t11][setxcor xcor + :hx setycor :y] ask [t1] [ifelse :y1 < 0 [setPC 4] [setPC 2] dot]
ask [t7] [ifelse :y2 < 0 [setPC 12] [setPC 1] dot]
ask [t5] [ifelse :y1 < 0 [setPC 4] [setPC 2] fd :y1 dot bk :y1 rt 1 / :n1 / :n2]
```

```

ask [t10] [ifelse :y2 < 0 [setPC 12] [setPC 1] fd :y2 dot bk :y2 rt 1 / :n1 / :n2]
ask [t11] [ifelse :y < 0 [setPC 13] [setPC 11] dot]
; mathematical convention
ask [t12] [ifelse :y < 0 [setPC 13] [setPC 11] fd :y dot bk :y rt 1 / :n1 / :n2 ]
; two-colour convention
;
ask [t12] [ifelse :y < 0 [setPC 13 bk :y dot fd :y] [setPC 11 fd :y dot bk :y]
;
rt 1 / :n1 / :n2 ]
]
end

```

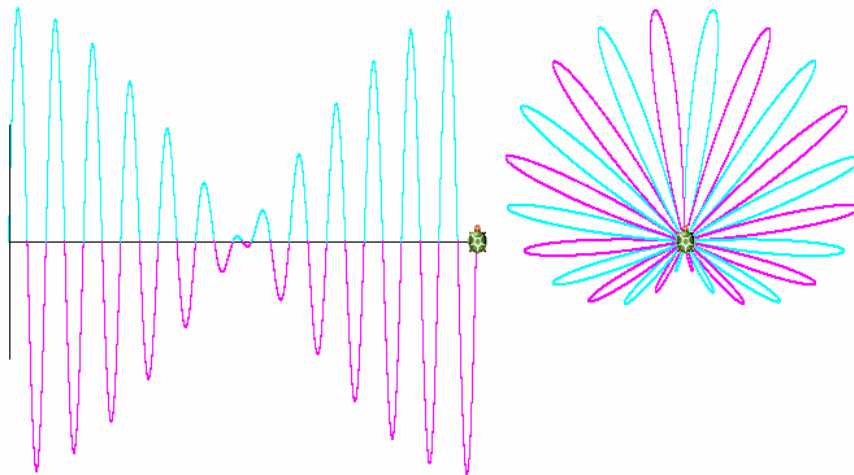


Fig. 8 The Cartesian and the polar (two-colour convention) plots of the superposition of two waves with parameters: 90 90 12 13 0 0 (beat)

Cycloids

A cycloid (Weisstein, 2003, 2004) is a plane curve that is the trajectory of a point lying on a circle that rolls without slipping along a straight line (regular cycloid) or upon another circle. A cycloid is called an epicycloid or hypocycloid, depending on whether the rolling circle has external or internal contact with the fixed circle. When the ratio of the radii of these two circles is rational, then the cycloidal curve is a closed algebraic curve.

In procedure `cycx` one turtle draws a regular cycloid combining two motions: circular motion (intrinsic equation of a circle, green colour) and translation in x direction (the extrinsic Cartesian coordinate system, blue colour).

```

to cycx :s
cs pu setxy -100 0 setheading 270
repeat 360 [dot fd :s rt 1 setxcor xcor + :s wait 10]
;circuference is 360 * s, radius is 180 * s / phi
end

```

The procedure `cyc` draws a regular cycloid on a wholly intrinsic way and may be simplified to the procedure `cyc1`:

```

to cyc
cs setPW 1 st setxy -100 0 setheading 270
repeat 360 [pd st setPC 12 fd 1 rt 1 wait 20
pu ht repeat repc [lt 1 bk 1]
pd st setPC 0 bk 1 wait 20
pu ht repeat repc [fd 1 rt 1]]
end

```

```

to cyc1 :s
cs pu setPW 1 ht setxy -100 0 setheading 270
repeat 360 [dot fd :s rt 1 repeat repc [lt 1] bk
:s repeat repc [rt 1]]
end

```

end

The main procedure for hypo- and –epicycloids could be as follows:

```
to hecycls :f :i :s
; i=-1 epi, i=1 hypo, f = 1, 2, 3, 4, ...
; dfl of fixed circle=const; s (scale) (from 1 to 2)
cs ht
repeat 360 [pd setPC 12 fd :s rt :i * :f
  pu repeat repc [lt :i * :f bk :s]
  pd setPC 0 lt 1 bk :s
  pu repeat repc [fd :s rt :i * :f]]
end
```

where parameter $f = n_1/n_2$ (ratio of frequencies).

Procedure hecycls could have two interesting modifications: hecyclsrt in which the direction of the rolling circle is the same as the fixed one and hecyclsm in which the centre of the rolling circle moves along the circumference of the fixed one.

```
to hecyclsrt :f :i :s
cs ht
repeat 360 [pd setPC 12 fd :s rt :i * :f
  pu repeat repc [lt :i * :f bk :s]
  pd setPC 0 fd :s rt 1
  pu repeat repc [fd :s rt :i * :f]]
end

to hecyclsm :f :i :s
cs ht
repeat 360 [pd setPC 12 lt 90 fd :s rt :i * :f
  pu repeat repc [lt :i * :f bk :s]
  pd setPC 0 rt 90 lt 1 bk :s lt 90
  pu repeat repc [fd :s rt :i * :f] rt 90]
end
```

We can create the whole family of cycloidal curves in quite a different way. In the procedures hypoepicyc and hypoepicyc1 the parameters s_1 and s_2 are the steps of arc lengths (these values are directly proportional to the radiuses) of the rolling and fixed circles, parameters n_1 and n_2 are the frequencies of these two circular motions. In each of these procedures for the same n_1 and n_2 , the ratio of frequencies is the same, but is obtained in a different way and in consequence the first procedure draws slower and more accurate than the second one.

```
to hypoepicyc :s1 :s2 :n1 :n2 :i
; hypo i = 1, epi i = -1
cs pu
repeat 360 * :n1 * :n2
[setPC 12 setPW 2 dot fd :s1 / :n2 rt :i / :n2
repeat repc [lt :i / :n2 bk :s1 / :n2]
setPC 0 setPW 1 dot lt 1 / :n1 bk :s2 / :n1
repeat repc [fd :s1 / :n2 rt :i / :n2]]
end

to hypoepicyc1 :s1 :s2 :n1 :n2 :i
; faster but with low quality
cs pu setPW 2
; additional with phase difference :p
; repeat :p / :n1 [fd :s1 * :n1 rt :i * :n1]
repeat 360 [setPC 12 dot fd :s1 * :n1 rt :i * :n1
repeat repc [lt :i * :n1 bk :s1 * :n1]
setPC 0 dot lt :n2 bk :s2 * :n2
repeat repc [fd :s1 * :n1 rt :i * :n1]]
end
```

If in the procedures hypoepicyc and hypoepicyc1 $lt :n_2$ change to $rt :n_2$ hypocycloid change into epicycloid with the same parameters and vice versa.

The “natural” cycloids created by the procedure hecycls could be obtained by generalized procedure hypoepicyc for the data fulfilled the basic cycloidal rule:

$$\frac{s_1}{s_2} = \frac{r_1}{r_2} = \frac{n_2}{n_1} = \frac{1}{f}$$

For example, the results of hecycls 3 1 1, hecycls 3 1 1.5, hypoepicyc 1 3 3 1 1 and hypoepicyc .5 1.5 3 1 1 differ only with the size.

Below is the version of the hypoepicyc procedure realized with three turtles: t1 draws the cycloid, t3 draws the fixed circle, t3 is invisible and cooperates with t1 and t2 in transferring the Cartesian coordinates and the turtle heading.

```

to turtles
repeat 2 [new "Turtle []]
ask [t1 t2 t3] [setHomestate [[-100 0]0]]
end

to hypoepicyc2 :s1 :s2 :n1 :n2 :i
cs ask [t1 t2 t3][pu] ask "t2 [ht]
ask "t1 [ pd setPW 2 setPC 12] ask "t3 [setPC 0 setPW 1]

repeat 360 * :n1 * :n2
[ask "t2 [setpos ask "t1 [pos] setheading ask "t1 [heading] repeat repc - 1 [lt :i / :n2 bk :s1 / :n2]]
ask "t3 [setpos ask "t2 [pos] pd lt 1 / :n1 bk :s2 / :n1 pu]
ask "t2 [setpos ask "t3 [pos] setheading ask "t3 [heading] repeat repc - 1 [fd :s1 / :n2 rt :i / :n2]]
ask "t1 [setpos ask "t2 [pos] setheading ask "t2 [heading] fd :s1 / :n2 rt :i / :n2]]
end

```

Let us see only one the most interesting modification: the fixed circle is additionally modified by the cycloid. Compare for example hypoepicyc2 1 3 3 1 1 with hypoepicyc3 1 2 2 1 1 and hypoepicyc3 2 1 1 2 1.

```

to hypoepicyc3 :s1 :s2 :n1 :n2 :i
cs ask [t1 t2 t3][pu] ask "t2 [ht]
ask "t1 [ pd setPW 2 setPC 12] ask "t3 [setPC 0 setPW 1]

repeat 360 * :n1 * :n2
[ask "t2 [setpos ask "t1 [pos] repeat repc - 1 [lt :i / :n2 bk :s1 / :n2]]
ask "t3 [setpos ask "t2 [pos] pd lt 1 / :n1 bk :s2 / :n1 pu]
;or pd fd :s2 / :n1 pu rt 1 / :n1]
ask "t2 [setpos ask "t3 [pos] repeat repc - 1 [fd :s1 / :n2 rt :i / :n2]]
ask "t1 [setpos ask "t2 [pos] fd :s1 / :n2 rt :i / :n2]]
end

```

Cartesian and polar plots of the cycloidally modulated waves

We can ask what are the shapes of the Cartesian and the polar functions created by cycloidal motion instead of circular one. Below is one of the many possible procedures; the cycloid is drawn by turtle t4.

```

to sinepolar3 :s1 :s2 :n1 :n2 :i
let "hx 2 * :s2 / :n1 / :n2 / 3.14
;initial positions for turtles
home ask [t1 t2 t3 t4][pu setpos [-300 0]pd]
;ask "t4 [repeat :p [fd :s rt 1]]]
ask "t1 [pu setycor ask "t4 [ycor] pd] ask [t1 t5][setPW 2 pu] ask [t4] [ht pu] ask "t5 [ht]

repeat 360 * :n1 * :n2 [ask [t4] [setPC 1 dot lt 90 fd :s1 / :n2 rt :i / :n2
repeat repc [lt :i / :n2 bk :s1 / :n2]
setPC 0 dot rt 90 fd :s2 / :n1 rt 1 / :n1 lt 90
repeat repc [fd :s1 / :n2 rt :i / :n2] rt 90 ]
let "y ask "t4 [ycor]
ask [t1 t2] [setxcor xcor + :hx]
ask [t1 t3] [setycor :y]
ask [t1] [ifelse :y < 0 [setPC 4] [setPC 2] dot]
ask [t5] [ifelse :y < 0 [setPC 4] [setPC 2] rt 1 / :n1 / :n2 fd :y dot bk :y]]

end

? cs sinepolar3 1 2 3 1 1
? sinepolar3 1 2 5 1 -1

```

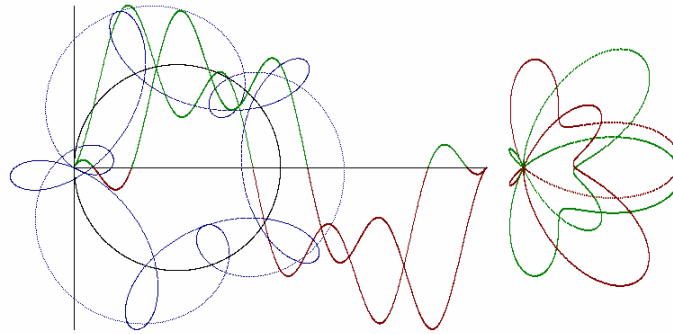


Fig. 9 Two Cartesian and polar functions created by two cycloidal motions (the centre of the rolling circle moves along the circumference of the fixed one).

Cycloidally modulated Lissajous curves

Also Lissajous curves could be modulated by cycloidal motion giving a wide variety of shapes. Below there is the procedure Lissajouscycloid, which is a modification of the procedure Lissajous1 – turtle t3 draws cycloid, turtle t4 usual circle. Turtle t5 takes xcor from t4 and ycor from t3 and draws cycloidally modified Lissajous curve.

```
to Lissajouscycloid :s1 :s2 :s3 :p :n1 :n2 :n3 :i
; s3, n3: rolling circle (t3), s1, n1: fixed circle (t3), s2, n2, p: usual circle (t4), hypo i = 1, epi i = -1
; amplitudes
cs make "r1 180 * :s1 / 3.14 make "r2 180 * :s2 / 3.14
; initial position for turtles
ask "t3 [ht hop -:r1 0 pu] ask "t4 [hop 0 :r2 rt 90 pu repeat :p [fd :s2 rt 1] pd]
ask "t5 [pu setxcor ask "t4 [xcor] setycor ask "t3 [ycor] pd setPW 2]
ask [t3 t4] [setPW 1] let "g GCD (GCD :n1 :n3) :n2
repeat 360 * :n1 * :n2 * :n3 / :g [ask [t3] [dot fd :s3 / :n1 / :n2 rt :i / :n1 / :n2
repeat repc [lt :i / :n1 / :n2 bk :s3 / :n1 / :n2]
fd :s1 / :n2 / :n3 rt 1 / :n2 / :n3
repeat repc [fd :s3 / :n1 / :n2 rt :i / :n1 / :n2]]
ask [t4] [fd :s2 / :n1 / :n3 rt 1 / :n1 / :n3]
ask [t5] [setxcor ask "t4 [xcor] setycor ask "t3 [ycor]]]]
end
```

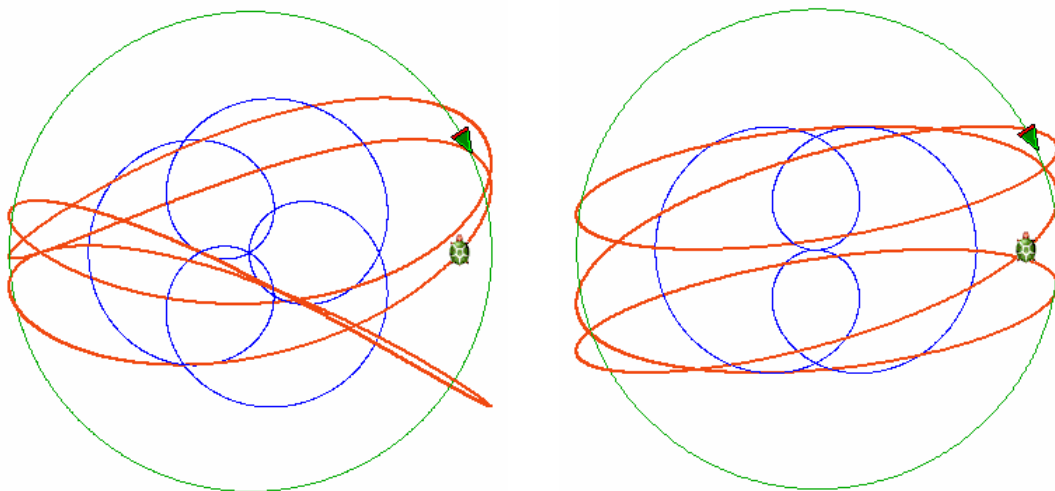


Fig. 10 Curve Lissajous 2 3 60 1 3 cycloidally modulated.

? Lissajouscycloid 2 3 1 60 1 3 3 1

? Lissajouscycloid 2 3 1 60 1 3 2 1

Comments

Playing with all these above presented programs we should not forget about two recurrent (or its iterative versions) procedures: the one creating a polar plot of a given function and the general procedure creating a curve of the intrinsic curvature described by a given function of ϕ variable (Armon, .1997).

```
? cs pu
to polarec :s :fi :kfi :fun :lfi
  if :fi > :lfi [stop]
  let "r :s * run :fun
  ifelse :r < 0 [setPC 4]
    [setPC 2] fd :r dot bk :r rt :kfi
  polarec :s :fi + :kfi :kfi :fun :lfi
end

? cs pd
to intr_graph :s :fi :kfi :fun :lfi
  if :fi > :lfi [stop]
  rt 1 let "ds :s * run :fun
  ifelse :ds < 0 [setPC 4]
    [setPC 2] fd :ds
  intr_graph :s :fi + :kfi :kfi :fun :lfi
end
```

In my opinion it is worth trying to create different curves in different ways, to compare them, to classify them in a new way, to generalize them, because there are several problems connected with the intrinsic representations of mathematical curves and also connected with the physical meaning of the concept of motion, that have not been solved yet or, at least, that are not well and simply described on the educational level.

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