On Flexible Dynamic Trait Replacement for JAVA-like Languages

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Abstract

Dynamic trait replacement is a programming language feature for changing the objects’ behavior at runtime by replacing some of the objects’ methods. In previous work on dynamic trait replacement for JAVA-like languages, the object’s methods that may be replaced must correspond exactly to a named trait used in the object’s class definition. In this paper we propose the notion of replaceable: a programming language feature that decouples trait replacement operation code and class declaration code, thus making it possible to refactor classes and to perform unanticipated trait replacement operations without invalidating existing code. We give a formal account of our proposal through a core calculus, FDTJ (FEATHERWEIGHT DYNAMIC TRAIT JAVA), equipped with a static type system guaranteeing that in a well-typed program no runtime type error will take place.

Key words: Featherweight Java, Trait, Type System

1. Introduction

The term \textit{trait} was used by Ungar et al. \cite{38,37}, in the dynamically-typed prototype-based language SELF, to describe a parent object to which an object may delegate some of its behavior. Subsequently, Schärl et al. \cite{35,14} introduced traits in the dynamically-typed class-based language SQUEAK/SMALLTALK as a mechanism for fine-grained reuse. A trait is a set of methods completely independent from any class hierarchy. Traits can be composed to form new traits or classes and trait composition supports code reuse better than (single and multiple) class-based inheritance. They can be composed in an arbitrary order and require the composed trait or class to resolve possible name conflicts explicitly. These features make traits more flexible and semantically simpler than mixins \cite{10,25,16,3}. Because of their flexibility and simple semantics, traits have attracted a great deal of attention and various formulations of traits within a nominal JAVA-like type system can be found in the literature (see, e.g., \cite{36,28,26,33,9}). A form of trait construct is present also in the recent programming language FORTRESS \cite{2} (where there is no class-based inheritance), while the “trait” construct incorporated in SCALA \cite{29} is indeed a form of mixin.

Dynamic trait replacement is the ability to change the behavior of an object at runtime by replacing one trait for another. (Dynamic trait replacement was listed as an issue for further work in the papers on traits in the dynamically-typed language SQUEAK/SMALLTALK \cite{35,14}.) In the prototype-based language SELF dynamic trait replacement can be achieved by changing the reference to the parent of an object. In the class-based setting, dynamic trait replacement has been formalized by Smith and Drossopoulou through the JAVA-like language Chai\textsubscript{3} \cite{36}. The language Chai\textsubscript{3} contains an operator for replacing a trait in an existing object. This operator requires that the trait to be replaced corresponds exactly to a named trait used in the object’s class definition. That is, the sets of methods that may be dynamically replaced are fixed in the object’s class definition and the trait replacement operations are coupled to the names of the traits used in the object’s class definition.

In this paper we propose a more flexible dynamic trait replacement operator. A distinguishing feature of our proposal is the notion of replaceable, a feature that provides a means to decouple trait replacement operation code and
class declaration code, thus enabling class refactoring and unanticipated trait replacement operations without invalidating existing code. We give a formal account of our proposal through a core calculus, FDTJ (FEATHERWEIGHT DYNAMIC TRAIT JAVA), equipped with a static type system guaranteeing that in a well-typed program no runtime type error will take place. A preliminary version of the material presented in this paper appeared as [6].

Organization of the paper. Section 2 presents some background and motivation. Section 3 illustrates our proposal through examples. Section 4 presents syntax, type system and operational semantics of FDTJ, a minimal core calculus for dynamic trait replacement. Section 5 shows that the FDTJ static type system is sound: it ensures that in a well-typed program no runtime error will take place. Section 6 discusses some related work. We conclude by summarizing the paper and outlining possible directions for further work.

2. Background and Motivation

The only dynamic feature in JAVA-like languages is represented by dynamic binding, i.e., the dynamic selection of a specific method implementation according to the runtime type of an object. This is not enough for representing the dynamic evolution of objects that behave differently depending on their internal state, the context where they are executing or the entities they interact with. All these possible behaviors may not be completely predictable in advance and they are likely to change after the application has already been developed and used. While trying to forecast all the possible evolutions of system entities, classes are often designed with too many responsibilities, most of which are basically not used. Furthermore, the number of subclasses tend to grow dramatically when trying to compose different functionalities into single modules.

Design patterns [18] are a programming techniques enabling to overcome some problematic deficiencies present in class based object-oriented programming languages. For instance to extend and change dynamic objects behavior at runtime in a class based context we can use Decorator and State pattern respectively. Design patterns are useful, however they require manual programming (decreasing productivity). The programmer should explicitly comment the code about the patterns used and their correct usage, but this still remains an informal specification, and most of the responsibility is left to the user of such implemented components. On the contrary our linguistic extension also “documents” the code [11]. For instance, the replaceable construct can be seen as an abstraction of objects’ roles/modes that directly highlights the main concept underneath its use (see, e.g., RPolicy in Listing 9 and RClassification in Listing 10). The correct use of the new linguistic constructs can be checked statically and once proved correct, their usage is guaranteed, at runtime, not to produce any run-time type errors.

With dynamic traits we achieve, in a class-based statically-typed setting, part of the dynamic flexibility typical of prototype-based languages [38, 37]. Moreover, with dynamic traits, we try to shorten the distance between the language features and the design patterns, so that their implementation can be smoother [7]. We do not aim at replacing design patterns completely: design patterns will keep on providing “a high-level language of discourse for programmers to describe their systems and to discuss common problems and solutions” [8]. Language features should make the application of a pattern easier and possibly more efficient [8]. For instance, implementations of patterns were proposed using aspect-oriented programming [21] and collaboration-based design [24].

Summarizing, we are not claiming that dynamic traits and their runtime features allow the programmers to implement some development scenarios which would not be implementable simply by using design patterns. We claim instead that, by using the proposed linguistic features, the programmer can express the structure and the interaction relations in a specific context directly, with less additional manual programming; furthermore, as linguistic features with their own additional typing system and operational semantics (which was proved sound), dynamic traits represent a flexible and safe programming mechanism. After all, one could do even without inheritance and dynamic binding, but one would need to implement these mechanisms from scratch in many development scenarios, and such manual implementations, besides being tedious and time consuming, would not enjoy the same safety properties of those provided by the linguistic constructs themselves (“Our patterns assume Smalltalk/C++-level language features, and that choice determines what can and cannot be implemented easily. If we assumed procedural languages, we might have included design patterns called Inheritance, Encapsulation, and Polymorphism.” [18]).

Some works, such as [17, 20], provide programming tools to help the programmer implement and use design patterns: it is possible to describe patterns, instantiate them (possibly starting from templates), merge them into the existing programs, check their correct implementation and usage, and also recognize them in the source code. Thus,
interface IAccountState {
    double calculateInterests(double d);
    void sendSumm(Address a);
}

class CGoldAccount implements IAccountState {
    double calculateInterests(double d) {...}
    void sendSumm(Address a) {...}
}

class CStandardAccount implements IAccountState {
    double calculateInterests(double d) {...}
    void sendSumm(Address a) {...}
}

class CBadAccount implements IAccountState {
    double calculateInterests(double d) {...}
    void sendSumm(Address a) {...}
}

class CAccount {
    double balance;
    Address a;
    IAccountState state;

    void changeState(IAccountState s) { state = s; }
    double getBalance() { return balance; }
    double calculateInterests() { return state.calculateInterests(balance); }
    void sendSumm() { state.sendSumm(a); }
}

Listing 1: The account example using the State pattern

dynamic method replacement at the linguistic level. However, we believe that the value of these tools would still be profitable in order to have a higher level view also of traits and replaceables.

2.1. An Example

The design pattern State [18] is often used in contexts where we need to change object behaviors at runtime according to their state; however, it still requires manual programming, and, it does not scale well to unanticipated extensions of the class hierarchy.

For instance, let us consider bank customers that can be classified as Gold, Standard or Bad according to their reliability. In Listing 1 the interface IAccountState, the classes CStandardAccount, CBadAccount, CGoldAccount and CAccount represent a possible implementation using the State design pattern. The interface IAccountState includes methods calculateInterests used to calculate interests (according to the balance and the class of the customer) and sendSumm sending to the customer’s address a monthly summary of the operations made on the account. Class CAccount includes an attribute of type IAccountState used to switch the state of the current account through method changeState. The execution of methods belonging to the interface IAccountState are delegated to the attribute state that, thanks to dynamic binding, performs the body of the method associated to the current state of the account. The state can change after a check of the associated balance as in the following code:

void checkCustomer(CAccount c) {
    if (c.getBalance() < 0) { c.changeState(new CBadAccount()); }
    else if (c.getBalance() > 1000) { c.changeState(new CGoldAccount()); }
Now suppose that a new, unanticipated category of customers has to be modeled: customers can decide to switch to an online-only account which is less expensive and does not send the monthly summary. The problem is that this feature is independent from the customers’ state: online customers can still be Gold, Standard and Bad. The hierarchy in Listing 1 has to be extended by adding the three following subclasses (where OL stands for online):

```java
class COLGoldAccount extends CGoldAccount { void sendSumm(Address a) {} }
class COLStandardAccount extends CStandardAccount { void sendSumm(Address a) {} }
class COLBadAccount extends CBadAccount { void sendSumm(Address a) {} }
```

Then, when transforming an account in a online one we have to check its state to find the right subclass:

```java
void setOnline(CAccount b){
    if (b instanceof CGoldAccount) { c.changeState(new COLGoldAccount()); }
    else if (b instanceof CBadAccount) { c.changeState(new COLBadAccount()); }
    else if (b instanceof CStandardAccount) { c.changeState(new COLStandardAccount()); }
}
```

This solution based on the State pattern is not so flexible w.r.t. unanticipated extensions since the combination of new features with preexisting states causes subclasses explosion; moreover the code to change the state (as the setOnline method above) is cumbersome and error prone in case of multiple combinations of state-dependent features.

To avoid the explosion of subclasses, one could use the decorator pattern together with the state pattern: this way the online state would be a decorator of the other states. However, this requires additional programming, and might also require to refactor the state hierarchy in order to take in consideration also decorators. Indeed, the Online decorator class would have a reference to a bank account, would redefine the method sendSumm as empty and would forward all the other methods to the bank account reference. Furthermore, if the bank account changes in the future, then also the decorator classes will have to be adapted.

3. Introducing Traits, Dynamic Trait Replacement and Replaceables

In Sections 3.1, 3.2 and 3.3 we introduce the notions of trait, dynamic trait replacement and replaceable through simple examples about data structures for sequences. Then in Section 3.4 we code the account example of Section 2.1 using our new language constructs. In the examples we exploit a Java-like notation and use a more general syntax (including, e.g., the types void and int, the assignment operator, etc.) than the one of the calculus that we will present in Section 4.

3.1. Introducing Traits

Consider the development of a class FifoSequence, by means of a First-in-first-out policy, implementing the interface ISequence in Listing 2.

In a language with traits the class FifoSequence can be developed by first introducing a trait TFifo providing the methods (see Listing 2) and then composing the class, by exploiting the trait, as follows

```java
class FifoSequence implements ISequence by TFifo {
    List l; // provided field
    FifoSequence() { this.l = new LinkedList(); } // constructor
}
```

Subsequently, a class LifoSequence implementing the ISequence interface by means of a Last-in-first-out policy can be developed by reusing the methods in and isEmpty provided by the trait TFifo to define the trait TLifo in Listing 3 (the operation exclude forms a new trait by excluding a method from a given trait and the sum operation, +, merges two traits to form a new trait — see [14, 9]). The class LifoSequence can be defined as follows

```java
class LifoSequence implements ISequence by TLifo {
    List l;
    LifoSequence() { this.l = new LinkedList(); }
}
```
### 3.2. Introducing Dynamic Trait Replacement

The classes `FifoSequence` and `LifoSequence` illustrate the use of traits as a static construct: the composition of traits into a class is fixed, once and for all, at compile time. For an example illustrating dynamic trait replacement consider the problem of developing a method `changePolicy` that takes as argument an instance `s` of the class `Sequence` of Listing 4, changes the extraction policy of `s`, extracts an element from `s` (according to the new policy), and terminates by changing further the insertion/extraction policy of `s`.

The Lexicographical-ordering extraction policy (that extracts elements from a sequence according to lexicographical ordering on the values returned by invoking the `toString` method on its elements) and the First-in-first-out insertion/extraction policy can be described by the traits `TLoExtractionPolicy` and `TFifoPolicy` in Listing 5, respectively.

During the execution, the extraction policy of the sequence `s` can be changed into Lexicographical-ordering by means of the trait replacement operation `s{TLoExtractionPolicy}`. Once the replacement has taken place, invoking the methods `get` and `out` will select the implementation of such methods as provided by `TLoExtractionPolicy`. The insertion/extraction policy can be then changed to First-in-first-out by executing the operation `s{TFifoPolicy}`. This is illustrated in the following code:

```java
void changePolicy(Sequence s) {
    s{TLoExtractionPolicy}; // (1)
    System.out.println(s.get());
    s.out();
    s{TFifoPolicy} // (2)
}
```

Note that there is no coupling between the definition of the class `Sequence` and the trait replacement operations. Consider, for instance, the need to develop the methods `disableIn` and `enableIn` that take a sequence object `s` and disable/enable the `in` operation without affecting the `get` and `out` operations. The methods `disableIn` and `enableIn` can be written, without changing the code of the class `Sequence`, by first defining the traits `TinDisabled` and `TinEnabled` in Listing 6. Then, the code of the methods is as follows

```java
void disableIn(Sequence s) {
    s{TinDisabled}; // (3)
}
void enableIn(Sequence s) {
    s{TinEnabled}; // (4)
}
```
class Sequence implements ISequence by TFifo {
    List l;
    Sequence() { this.l = new LinkedList(); }
}

Listing 4: The class Sequence

trait TLoExtractionPolicy is {
    List l; // required field
    void out() { /* provided method (removes the minimum element according to Lexicographical–ordering) */
        Object get() { /* provided method (returns the minimum element according to Lexicographical–ordering) */
    }
}

trait TFifoPolicy is {
    List l; // required field
    void in(Object o); // provided method
    void out(); // provided method
    Object get(); // provided method
}

Listing 5: The traits TFifoPolicy and TLoExtractionPolicy

s{TinEnabled}; // (4)
}

Since in the proposed approach there is no coupling between the definition of a class and the trait replacement operations on its instances, any change to the code of class Sequence that preserves the signatures of its methods does not affect existing trait replacement operations. For instance, the trait replacement operations (1), (2), (3) and (4) that have been written to deal with the class Sequence in Listing 4 are still valid when the class is rewritten, as in Listing 7, in order to make sequences to be created as Last-in-first-out sequences.

3.3. Introducing Replaceables

Consider the problem of developing a more general version of the method changePolicy of Section 3.2, let us call it changePolicy1, that can accept as argument an object s belonging to any class that implements the interface ISequence. Unfortunately, the signature

void changePolicy1(ISequence s)

is not able to guarantee at compile time that the dynamic replacement of the methods in, out and get of s is type safe. In fact it is not enough to simply check that the replacing methods have the same signatures as the replaced ones: these methods may rely on other methods and/or fields. In order to be able to statically type-check runtime method replacement when the static type of the target expression e of the replacement operation e{T} is not a class, we introduce the notion of replaceable as mean to specify these requirements.

A replaceable is a predicate over a set of methods. The syntax of a replaceable definition is as follows

\[
\text{replaceable } R \text{ is } \{S,; \langle G; ; Z,; J,; \rangle}
\]

where \( S \) and \( Z \) are disjoint sequences of method signatures (\( S \) are the methods they may be in the set and \( Z \) are the methods that may be used by the methods in the set), \( G \) is a sequence of fields (the fields that may be used by the methods \( S \cup Z \)) and \( J \) is a sequence of interface names (the interfaces that may be used as types of this within the bodies of the methods \( S \cup Z \)).

Interface names and replaceable names are used to form a novel kind of source language type that contains the information needed for statically type-checking runtime method replacement. Namely, given an interface I and a replaceable

\[
\text{replaceable } R \text{ is } \{S,; \langle G; ; Z,; J,; \rangle}
\]
trait TinDisabled is { void in(Object o) {} // provided method */ }

trait TinEnabled is { void in(Object o) { l.addFirst(o); } // provided method */ }

Listing 6: The traits TinDisabled and TinEnabled

class Sequence implements ISequence by TLifo {
    List l;
    Sequence() { this.l = new LinkedList(); }
}

Listing 7: A Last-in-first-out version of the class Sequence

I{R} is the type of references to any object whose class implements the interface I and has the methods described by the replaceable R. Through a reference of type I{R} it is possible to invoke on the referenced object the methods of the interface I and to replace, in the referenced object, any of the methods with signatures S by any trait that satisfies R. To ensure safety, the class of the referenced object must:

- implement all the interfaces I ∪ J;
- have all the fields G;
- have all the methods S ∪ Z.

A trait T (that is, a set of methods) satisfies the replaceable R if and only if T consists of methods whose signatures occur in S and whose bodies

- select only the fields G on this,
- select only the methods S ∪ Z on this,
- assume only the interfaces J as nominal types of this, i.e.,
  - pass this as argument to a method only if there exists an interface in J that is a subtype of the type of the corresponding formal parameter of the method, and
  - return this as result of a method only if there exists an interface in J that is a subtype of the return type of the method.

For instance, let us consider the replaceable RExample, the interfaces ISomeSequence and ISomeSequenceComparator and the traits TExample1 and TExample2 in Listing 8: RExample is satisfied by both TExample1 and TExample2.

Let EmptyR be a distinguished name for the replaceable defined by replaceable EmptyR is {•} {• ; • ; •}, which is satisfied only by the empty set of methods. According to the above description, for every interface I, we will identify the types I{EmptyR} and I.

Remark 3.1. While presenting the type system we will introduce the specification operator, which automatically extracts a replaceable definition from a trait (see Definition 4.12). In a full language, this operator would relieve programmers of the burden of writing all the details of replaceable declarations. For instance, the definition of the replaceable RExample in Listing 8 could also be written as: replaceable RExample is specificationof(TExample1).

Now we can go back to the problem of developing the changePolicy1 method. Consider the replaceable RPolicy in Listing 9. According to the above explanation, a variable s of type ISequence(RPolicy) can be assigned an instance of any class that implements the interface ISequence and has the methods described by the replaceable RPolicy (like the class Sequence in Listing 4). During the execution, the extraction policy of the sequence can be changed into Lexicographical-ordering by means of the trait replacement operation s{TLoExtractionPolicy}. Once
The replaceable RExample interface extends ISomeSequence

```java
interface ISomeSequence extends ISomeSequenceComparator {
    // provided method
    boolean test() {
        return c.compare(this, s);
    }
}
```

The replaceable RPolicy interface is

```java
interface RPolicy is {
    void out();
    Object get();
    void in(Object o);
}
```

Listing 9: The replaceable RPolicy

the replacement has taken place, invoking the methods get and out will select the implementation of such methods as provided by TLoExtractionPolicy. The insertion/extraction policy can be then changed to First-in-first-out by executing the operation s(TFifoPolicy). This is illustrated in the following code:

```java
void changePolicy1(ISequence<RPolicy> s) {
    s(TLoExtractionPolicy);  // (1')
    System.out.println(s.get());
    s.out();
    s(TFifoPolicy)  // (2')
}
```

The replaceable RPolicy describes both a subset of the methods of any class whose instances may be referenced through a variable of type ISequence<RPolicy> and a superset of the methods of the traits used by the trait replacement operations (1') and (2'); and this is all that is required to make the above code correct. The variant of the methods disableIn and enableIn of Section 3.2 that works on arguments of type ISequence<RPolicy> is as follows

```java
void disableIn1(ISequence<RPolicy> s) {
    s(TinDisabled);    // (3')
}
void enableIn1(ISequence<RPolicy> s) {
    s(TinEnabled);    // (4')
}
```

Note that the trait replacement operations (1'), (2'), (3') and (4') work with both the versions of the class Sequence given in Listings 4 and 7.
interface IAccount {
    double getBalance();
    double calculateInterests();
    void sendSumm();
}

trait TBaseAccount { double balance;
    double getBalance() { return balance; }
}

trait TStandardAccount { double balance; Address a;
    double calculateInterests() {...}
    void sendSumm() {...}
}

trait TGoldAccount { double balance; Address a;
    double calculateInterests() {...}
    void sendSumm() {...}
}

trait TBadAccount { double balance; Address a;
    double calculateInterests() {...}
    void sendSumm() {...}
}

class CAccount implements IAccount by TBaseAccount + TStandardAccount {
    double balance;
    Address a;

    CAccount(...) {...}
}

replaceable RClassification is { double calculateInterests(); void sendSumm(); }
< double balance; Address a; | | >

Listing 10: The account example using traits and replaceables
3.4. The Account Example

Let us come back to the example in Section 2.1 (Listing 10). The interface IAccount lists all the methods of account objects; then there are four traits: TBaseAccount implements those methods that are independent from reliability (getBalance) while traits TStandardAccount, TBadAccount and TGoldAccount implements reliability-dependent methods. The class CAccount implements the behavior of standard accounts by traits TBaseAccount and TStandardAccount. The replaceable RClassification is used to define references of type IAccount{RClassification}: the referenced objects can replace the implementation of the methods calculateInterests and sendSumm. Now let us implement method checkCustomer introduced in Section 2.1:

```java
void checkCustomer(IAccount{RClassification} c) {
    if (c.getBalance() < 0) c{TBadAccount};
    else if (c.getBalance() > 1000) c{TGoldAccount};
}
```

The parameter of the method is of type IAccount{RClassification}. With respect to the implementation in Section 2.1 we just have to perform the replaceable operation c{TSomeAccount} instead of: (i) creating a new object representing the state, and (ii) assign it to the corresponding c field through the method changeState. Later, to model online accounts, we just have to add a trait implementing the new version of sendSumm:

```java
trait TOnLine { void sendSumm() {} }
```

and then to declare the parameter of the setOnline method as IAccount{RClassification}:

```java
void setOnline(IAccount{RClassification} c) {
    c{TOnLine};
}
```

Using traits and replaceables we do not have subclass explosion and we do not have to use instanceof tests in the body of the method setOnline: we just have to write the replacement operation c{Online}. The benefits of our solution with respect to the State pattern can be summarized as in the following:

- the management of the state associated to an object, that is a dedicated field and a method to change it, is no more needed; and
- different sets of states depending on orthogonal features can be combined and added in a flexible way.

4. A Calculus for Dynamic Traits

In this section we introduce FDTJ (FEATHERWEIGHT DYNAMIC TRAIT JAVA), a minimal core calculus, in the spirit of FJ (FEATHERWEIGHT JAVA) [22], for interfaces, replaceables, traits, and classes. Since our goal is to provide a foundation for flexible dynamic trait replacement within a JAVA-like nominal type system, FDTJ does not model type casts, trait composition operations and class-based inheritance, which are orthogonal to dynamic trait replacement.

The distinguishing design choices of FDTJ are the following.

- The novel replaceable construct specifies methods that can be dynamically replaced in an object by other methods that satisfy the specification. It provides a means to decouple trait replacement operation code and class declaration code, making it possible to refactor classes and performing unanticipated trait replacement operations without invalidating existing code.
- The type system supports the typechecking of traits in isolation from the trait replacement operations that use them, so that it is possible to typecheck a method defined in a trait only once (instead of having to typecheck it in every trait replacement operation using that trait).
- Class names and trait names are not source language types. This choice allows us to simplify the calculus and to focus on the challenging problem of typing a dynamic trait replacement expression e{T} when the (compile-time) type of the expression e is not a class (Chai) [36] does not consider interfaces.
Extending the calculus with type casts and trait composition operations is straightforward. The corresponding rules can be obtained by adapting those presented in [9], where dynamic trait replacement is not considered, to deal with the richer types and constraints introduced in this paper. Moreover, adding class-based inheritance and allowing the programmer to use class names and trait names as types should not pose particular technical problems (it would just complicate the calculus).

4.1. Syntax

The syntax of FDTJ is presented in Figure 1. We use the overbar sequence notation according to [22]. For instance, the pair “\( \overline{UX} \)” stands for “\( U_1x_1,...,U_nx_n \)”, and “\( \overline{UT} \)” stands for “\( U_1f_1,...,U_nf_n \)”. The empty sequence is denoted by “\( \cdot \)” and the length of a sequence \( S \) is denoted by \(|S|\). Sequences of named elements (interface definitions, method headers, method definitions, etc.) are assumed to not contain elements with the same name. Given a sequence of named elements \( D \), the sequence of the names of the elements of \( D \) is denoted by \( \text{names}(D) \). The subsequence of the elements of \( D \) with the names \( n \) is denoted by \( \text{choose}(D,n) \), and \( \text{exclude}(D,n) \) denotes the sequence obtained from \( D \) by removing the elements with the names \( n \). We use a set-based notation for operators over sequences of named elements. In the union and in the intersection of sequences, denoted by \( S \cup Z \) and \( S \cap Z \), respectively, it is assumed that if \( n \in \text{names}(S) \) and \( n \in \text{names}(Z) \) then \( \text{choose}(S,n) = \text{choose}(Z,n) \). The empty sequence is \( \emptyset \).

A trait definition \( \text{trait } T \text{ is } TE \) associates a trait name \( T \) to a trait expression \( TE \). A trait expression is either a basic trait expression or a trait name. A basic trait expression \( \{ F; S; M \} \) defines methods \( M \) and declares required fields \( F \) and fields \( S \) (where \( \text{names}(S) \cap \text{names}(M) = \emptyset \)). Required fields and methods can be directly accessed (i.e., selected on this) within the bodies of the methods \( M \).

A class definition \( \text{class } C \text{ implements } I \text{ by } TE \{ F; K \} \) defines its fields, \( F \), and the constructor, \( K \), which shows how to initialize all the fields with the received arguments. The class does not directly define the methods of its interface \( I \); it relies on a trait expression \( TE \) for this (with the clause \text{by}).

The subset of FDTJ obtained by removing the portions of the syntax highlighted in gray maps to a subset of JAVA. Namely, the FDTJ class \( \text{class } C \text{ implements } I \text{ by } \{ F; \cdot; M \} \{ G; K \} \) (where the required field declarations \( F \) are a subset of the provided field declarations \( G \)) can be understood as the JAVA class \( \text{class } C \text{ implements } I \{ G; K M \} \).

The expression \( e[T] \) describes the dynamic replacement, in the object denoted by \( e \), of the methods defined by the trait \( T \) for the corresponding methods of the object. For instance, if \( T \) is defined by \( \text{trait } T \text{ is } \{ F; S; M \} \), then the methods of object \( e \) with names \( \text{names}(M) \) will be replaced by the methods \( M \).

A replaceable definition \( \text{replaceable } R \text{ is } \{ S; F; L; T; \} \) defines a replaceable of name \( R \).

A class table \( CT \) is a map from class names to class declarations. Similarly, an interface table \( IT \), a trait table \( TT \), and a replaceable table \( RT \) map interface, trait, and replaceable names to interface, trait and replaceable declarations, respectively. An FDTJ program is a 5-tuple \( (IT; TT; RT; CT; e) \), where \( e \) is the expression to be executed. Following
FJ [22], in presenting the type system and the operational semantics we assume fixed, global tables IT, TT, RT, and CT. We also assume that these tables are well-formed, i.e., they contain an entry for each interface/trait/replaceable/class mentioned in the program, and the interface subtyping and trait reuse graphs are acyclic. In the following, instead of writing CT(C) = class C ... we will simply write class C ...; the same convention will be used for interfaces, replaceables and traits.

4.1.1. Lookup Functions and Method Signatures

In order to define FDTJ well-formed source language types, typing rules, and reduction rules we need a few lookup functions, given in Figure 2. The fields of a class C or required by a replaceable R are denoted by fields(C) and fields(R), respectively. Given a source language type U = I[R], we write fields(U) to denote the fields required by R.

The interfaces implemented by the class C are denoted by interfaces(C). Given a source language type U = I[R], we write interfaces(U) to denote the interface name I, while allInterfaces(U) denotes the sequence formed by the interface name I and all the interface names listed in the replaceable R.

The methods of a class C or of a trait expression TE are denoted by methods(C) and methods(TE), respectively.

Method signatures, ranged over by σ and ζ, are method headers deprived of parameter names. The signature associated to the method header S and the signature associated to the method definition M are denoted by mSig(S) and mSig(M), respectively. We write mSig(C) and mSig(I) to denote the signatures of all the methods of the class C and the signatures of all the methods of the interface I, respectively. Given a source language type U = I[R] we write mSig(U) to denote the sequence containing the signatures of the interface I, the signatures of the method headers occurring in R and the signatures of the interfaces whose names are listed in R. Note that the lookup function mSig(·) is also defined on sequences.

Convention 4.1. Since, in the method headers listed in a replaceable definition replaceable R is {S₁, S₂, ..., Sₙ}, the names of the parameters of the methods are immaterial, in the following we will sometimes write replaceable definitions by using method signatures instead of method headers.

4.1.2. Well-Formed Source Language Types

A source language type U is well-formed if and only if the lookup mSig(U) is defined, that is, there are no conflicts in the collected method signatures (recall that: sequences of method signatures are assumed to not contain signatures with the same method name); in the union of sequences, σ ∪ ζ, it is assumed that if n ∈ names(σ) and n ∈ names(ζ) then choose(σ, n) = choose(ζ, n); and in the disjoint union of sequences, σ · ζ, it is assumed that names(σ) ∩ names(ζ) = ∅. We assume that all the source language types occurring in a program are well-formed.

4.2. Typing

In order to be useful in practice a JAVA-like nominal type system for static and dynamic traits has to support the typechecking of traits in isolation from both the trait (static) composition and (dynamic) replacement operations that use them, so that it is possible to typecheck a method defined in a trait only once (instead of having to typecheck it in every trait composition or replacement operation using that trait).

The FDTJ type system supports the above property through the use of constraints and the use of a suitable combination of nominal and structural typing. Within a basic trait expression, the uses of method parameters are type-checked according to the nominal notion of typing defined by the interface hierarchy and to a structural notion of typing for replaceables, while the uses of this are type-checked according to a structural notion of typing that takes into account the fields and methods required by the trait and the methods provided by the trait.

4.2.1. Types and Constraints

The syntax of source language types, ranged over by U and V, has been already given in Figure 1. Pseudo-nominal types, ranged over by π, are either class names or a source language types (remember that, as explained in Section 3.3,
Fields lookup (function fields):
\[
\begin{align*}
\text{fields}(C) &= F \quad \text{if class } C \text{ implements } I \\
\text{fields}(R) &= F \quad \text{if replaceable } R \text{ is } \{ \ldots \} R \ldots \\
\text{fields}(I[R]) &= \text{fields}(R)
\end{align*}
\]
Interfaces lookup (functions interfaces and allInterfaces):
\[
\begin{align*}
\text{interfaces}(C) &= I \quad \text{if class } C \text{ implements } I \text{ by } \\
\text{interfaces}(I[R]) &= I \quad \text{if replaceable } R \text{ is } \{ \ldots \} R \ldots \\
\text{allInterfaces}(I[R]) &= I \cup J \quad \text{if replaceable } R \text{ is } \{ \ldots \} R \ldots 
\end{align*}
\]
Methods lookup (function methods):
\[
\begin{align*}
\text{methods}(C) &= \text{methods}(TE) \quad \text{if class } C \text{ by } TE \{ \ldots \} \\
\text{methods}(T) &= \text{methods}(TE) \quad \text{if trait } T \text{ is } TE \\
\text{methods}(\{ \ldots ; ; ; M \}) &= M
\end{align*}
\]
Method signatures lookup (function mSig):
\[
\begin{align*}
\text{mSig}(U m(U_1 x_1, \ldots, U_n x_n)) &= U m(U_1, \ldots, U_n) \\
\text{mSig}(S_1 \ldots S_n) &= \text{mSig}(S_1) \cdots \text{mSig}(S_n) \\
\text{mSig}(\{ \text{return } e \}) &= \text{mSig}(S) \\
\text{mSig}(M_1 \ldots M_n) &= \text{mSig}(M_1) \cdots \text{mSig}(M_n) \\
\text{mSig}(C) &= \text{mSig}(\text{methods}(C)) \\
\text{mSig}(C_1, \ldots, C_n) &= \text{mSig}(C_1) \cdots \text{mSig}(C_n) \\
\text{mSig}(l) &= \text{mSig}(l) \cup \text{mSig}(S) \quad \text{if interface } l \text{ extends } I \{ \ldots \} \\
\text{mSig}(l_1, \ldots, l_n) &= \text{mSig}(l_1) \cup \ldots \cup \text{mSig}(l_n) \\
\text{mSig}(l[R]) &= \text{mSig}(l) \cup \text{mSig}(S) \cup \text{mSig}(Z) \cup \text{mSig}(J) \quad \text{if replaceable } R \text{ is } \{ \ldots \} R \ldots \\
\text{mSig}(U_1, \ldots, U_n) &= \text{mSig}(U_1) \cup \ldots \cup \text{mSig}(U_n)
\end{align*}
\]

Figure 2: FDTJ: Lookup functions

for every interface \( I \) we identify the types \( I[\text{EmptyR}] \) and \( I \). The syntax of pseudo-nominal types is as follows:

\[
\pi ::= C \mid U
\]

The syntax of the structural types for the this pseudo-variable, ranged over by \( \tau \), is as follows:

\[
\tau ::= \langle \ F \ ; \ \sigma \rangle
\]

The pair \( \langle F ; \sigma \rangle \) specifies that this has the fields \( F \) and methods with signatures \( \sigma \). The syntax of the types for expressions, ranged over by \( \theta \), is as follows:

\[
\theta ::= \pi \mid \tau
\]

That is, a type for expressions is either a pseudo-nominal type or a structural type for this.

Besides assigning to each expression \( \theta \) a type describing the object yielded by the evaluation of \( \theta \), the FDTJ type system infers also the constraints on this imposed by its use within \( \theta \) (this-constraints) and the constraints on traits imposed by the dynamic trait replacement expressions within \( \theta \) (trait-constraints).

- The syntax of this-constraints, ranged over by \( \gamma \), is as follows:

\[
\gamma ::= \langle \ F \ ; \ \sigma \ ; \ U \rangle
\]

The triple \( \langle F ; \sigma ; U \rangle \) specifies that the expression \( \theta \) selects the fields \( F \) and the methods \( \sigma \) on this, and requires that this has the types \( U \). In particular, the types \( U \) are the types of the method’s formal parameters to which this is passed inside the expression \( \theta \). We recall that this will assume a meaning according to the class where the traits will be used.

- Trait-constraints, ranged over by \( \delta \), are sets of trait-replaceable inclusions. The syntax of trait-replaceable inclusions, ranged over by \( \delta \), is as follows:

\[
\delta ::= T \in R
\]

The pair \( T \in R \) specifies that the set of methods defined by the trait \( T \) satisfies (according to Definition 4.6) the replaceable \( R \).

---

1The term “pseudo-nominal” aims to recall that these types include both nominal types (classes and interfaces) and types of the shape \( I[R] \) (the source level types) that are composed by that is a nominal type (the interface name \( I \)) and another component (the replaceable name \( R \)) that is not a nominal type.
4.2.2. Subtyping Rules

Subtyping rules:

\[
\begin{align*}
\text{interface } I \cdots & \quad \text{interface } I \text{ extends } J \{ \cdots \} \quad J \in J \quad l_1 \subseteq l_1 \quad l_1 \subseteq l_2, \\
\text{Replaceable inclusion rule:} & \quad \text{replaceable } R \text{ is } \{S; \ G; \ Z; J\} \quad \text{replaceable } R' \text{ is } \{S'; \ G'; \ Z'; J'\} \\
& \quad m\text{Sig}(S) \subseteq m\text{Sig}(S') \quad G \subseteq G' \quad m\text{Sig}(S \cup Z) \subseteq m\text{Sig}(S' \cup Z') \quad \forall J \in J, \exists J' \in J', \ J' \subseteq J \\
& \quad R \subseteq R' \\
\text{Subtyping rules:} & \quad \text{class } C \text{ implements } J \text{ by } \ldots \\
& \quad \exists J \in J, J[R_C] \subseteq l[R] \quad I \subseteq I' \quad R \subseteq R' \\
& \quad C <:: C \\& \quad C <:: I[R] \\
\end{align*}
\]

Figure 3: FDTJ: Subinterfacing, replaceable inclusion, subtyping

Method types, ranged over by \(\mu\), are triples \(\zeta \vdash \gamma \vdash \Delta\) where \(\zeta\) is the method’s signature and \(\gamma\) and \(\Delta\) are the constraints inferred for the method’s body. The typing rule for classes will check that the this-constraints inferred for the bodies of the methods of the class are satisfied. Trait-constraints will be checked after checking all the trait definitions in the program, when the typings of all traits mentioned in the constraints will be available (see Definition 4.16).

Remark 4.2. The FDTJ type system collects constraints on a per-method basis, rather than on a per-trait basis (as usual in the nominal type systems that can be found in the literature). Collection constraints on a per-method basis has been proposed, in a structurally typed setting, by Reppy and Turon [32], and subsequently, in connection with a JAVA-like nominal type system, by Bono et al [9]. Both the proposals [32] and [9] do not consider dynamic trait replacement. Collecting method dependencies on a per-method basis is needed in order to be able to deal with the method exclusion operation (mentioned in Section 3.1). Since the FDTJ calculus does not include trait composition operations, the type system could be safely modified to collect constraints on a per-trait basis and to avoid to collect the constraints on fields and methods selected on this in the this-constraints inferred by the typing rules for expressions and method definitions given in Figure 5 (the typing rule for basic trait expressions, given in Figure 6, could simply take the declarations contained in the basic trait expressions). This would slightly simplify the presentation of the system. However, we have decided to collect constraint on a per-method basis since this makes it straightforward to extend the system to deal with trait composition operations by adapting the typing rules in [9].

4.2.2. Subtyping Rules

To simplify the presentation of the subtyping rules we introduce the specification of operation for classes. That is, a lookup function that, given a class name \(C\), returns a replaceable declaration right-hand side that “characterizes” the set of methods of \(C\).

Definition 4.3. Let class \(C\) implements \(I\) by \(\{F, K\}\). We define specification\((C)\) as \(\{m\text{Sig}(C); \{\{F, i; \bullet; I\}\}\}\).

Convention 4.4. For every class \(C\), we write \(R_C\) to denote a distinguished replaceable name (that cannot occur in source programs) and assume the replaceable definition replaceable\(R_C\) is specification\((C)\).

Subinterfacing, replaceable inclusion and subtyping rules are given in Figure 3. The subinterfacing relation is the reflexive and transitive closure of the immediate subinterfacing relation declared by the extends clauses in the interface table IT.

The replaceable inclusion rule models the fact that, if the replaceable \(R\) is included into the replaceable \(R'\), then every set of methods that satisfies (according to the explanation given in Section 3.3) \(R\) satisfies also \(R'\). Note that the replaceable inclusion relation is reflexive and transitive.

The subtyping relation is syntax directed. The first rule is the standard reflexivity rule for classes. Recall the meaning of types of the form \(l[R]\) (illustrated in Section 3.3). The second rule exploits Definition 4.3 and Convention 4.4, and then relies on the third rule. The third rule exploits the subinterfacing and replaceable inclusion relations (replaceable inclusion is exploited contra-variantly because replaceables are requirements, so a subtype cannot have more requirements). The rules integrate nominal subtyping (expressed by the implements clauses in the...
class table CT and by the subinterfacing relation) and structural subtyping (expressed by the replaceable inclusion relation, that exploits the replaceable component \( R \) of a source language type \( \{ \{R\} \} \) to ensure that the subtype has all the fields/methods and implements all the interfaces of the supertype). Note that transitivity is admissible.

**Example 4.5.** Consider the interface ISequence in Listing 2, the interface ISomeSequence in Listing 8, the replaceable RPolicy in Listing 9, and the following replaceable

\[
\text{replaceable RExtractionPolicy is } \{ \text{ void out(); Object get(); } \} < \text{List I; | | >}
\]

Both RExtractionPolicy \( \sqsubseteq \) RPolicy and ISomeSequence[RPolicy] \( < \) ISequence[RExtractionPolicy] hold. Consider also the replaceable RExample in Listing 8 and the replaceable RAnotherExample in Example 4.7.

Both RAnotherExample \( \sqsubseteq \) RExample and ISomeSequence[RExample] \( < \) ISomeSequence[RAnotherExample] hold.

### 4.2.3. On the Meaning of Replaceables and Replaceable Inclusion

A replaceable is a predicate over a set of methods (that is, over a trait). The following definition describes in a precise way, by relying on the subtyping relation defined in Figure 3, when a set of methods satisfies a replaceable (this definition has been already illustrated in Section 3.3, when no definition of the subtyping relation was available).

**Definition 4.6.** A set of methods satisfies the replaceable replaceable \( R \) is \( \{ S; G; Z; J; \} \) if and only if the set consists of methods whose signatures occur in \( \text{mSig}(S) \) and whose bodies

- select only the fields \( G \) on this,
- select only the methods \( S \cdot Z \) on this,
- assume only the interfaces \( J \) as nominal types for this, that is,
  - pass this as argument to a method only if there exists \( J \in J \) such that \( J\{ R \} \) is a subtype of the type of the corresponding formal parameter of the method, and
  - return this only if there exists \( J \in J \) such that \( J\{ R \} \) is a subtype of the return type of the method.

**Example 4.7.** Both the trait TFifoPolicy in Listing 5 and TinDisabled in Listing 6 satisfy the replaceable RPolicy in Listing 9. Instead, the trait TFifo in Listing 2 does not satisfy the replaceable RPolicy (because of method isEmpty).

Consider the replaceable RExample and the traits TExample1 and TExample2 in Listing 8. Both TExample1 and TExample2 satisfy RExample. The fact that TExample1 satisfies RExample relies on the fact that ISomeSequence[RExample] is a subtype of ISomeSequence (according to the subtyping relation \( < \) in Figure 3). The trait TExample2 satisfies also the following replaceable

\[
\text{replaceable RAnotherExample is } \{ \text{ void outTwice(); boolean isEmpty(); boolean test(); } \} < \text{ISomeSequenceComparator c; | void out(); | >}
\]

Instead, the trait TExample1 does not satisfy RAnotherExample because the code of the method isNotEmpty selects the method isEmpty on this and the code of the method test selects the field s on this and passes this as argument to a method with formal parameter ISomeSequence.

The following proposition illustrates the meaning of Definition 4.3 and Convention 4.4 in terms of Definition 4.6 (the proof is straightforward).

**Proposition 4.8.** If For every class \( C \), if \( M \) is the set of methods of \( C \), then \( M \) satisfies \( R_C \).

The following proposition states the soundness of the replaceable inclusion rule with respect to Definition 4.6 (the proof is straightforward).

**Proposition 4.9.** If \( R \sqsubseteq R' \), then every set of methods that satisfies \( R \) satisfies also \( R' \).
Figure 4: FDTJ typing rules for interface definitions and replaceable definitions

4.2.4. Typing Rules

A type environment, $\Gamma$, is either a finite mapping from variable names (including this) to types, written "$\tau: \mathcal{U}$", or the empty mapping, written "$\epsilon$". The typing rules for interface definitions, replaceable definitions, expressions, method definitions, trait definitions and class definitions are syntax directed, with one rule for each form of term.

The typing judgment for interface definitions is $\Gamma \vdash [\text{interface } I \text{ extends } J \{ S \} \text{ OK}]$ to be read: "the definition of the interface $I$ is well-typed". The associated rule, (I-Ok), is given in Figure 4. It exploits the lookup function $\text{mSig}([\cdot])$ to check that there are no conflicts in the signatures of the methods declared in the interface and in all its superinterfaces.

The typing judgment for replaceable definitions is $\Gamma \vdash [\text{replaceable } R \text{ is } \{ S, \{ Z \} : \{ J \} \text{ OK}]}$ to be read: "the definition of the replaceable $R$ is well-typed". The associated rule, (R-Ok), is given in Figure 4. It checks that, within a replaceable definition, the signatures of the methods that may be replaced ($S$) and the signatures of the methods that may be used by the replaced methods but may not be replaced ($Z$) are disjoint, and that there are no conflicts in all the the signatures of the methods declared in the trait ($S \cup Z$) or belonging to the interfaces that may be used as types for this ($J$).

The typing judgment for expressions is $\Gamma \vdash e : \theta \downarrow \gamma \downarrow \Delta$ to be read: "under the assumption in $\Gamma$, the expression $e$ is well-typed with type $\theta$ and constraints $\gamma$ and $\Delta$". The associated rules are given in Figure 5. The type of the pseudo-variable this is the structural type $\Gamma(\text{this})$. The type of an object creation expression $\text{new } C(\ldots)$ is the class name $C$. The type of any other FDTJ expression $e$ is a source language type, i.e., a type of the form $I\{R\}$ for some interface name $I$ and replaceable name $R$. The most interesting rules are the following.

- Rule (T-INVKTHIS) checks method invocation when the receiver is the this pseudo-variable. First the signature of $m$ ($\mathcal{U}(m(U_1, \ldots, U_n) = \zeta)$ is extracted from the sequence $\mathcal{S}$ associated to this. Then, the types of the actual parameters $e_1, \ldots, e_n$ are checked. For the arguments that are different from this ($e_i$ such that $i \notin \mathcal{T}$) the subtyping check between actual and formal parameter types is performed ($\theta_i <: U_i$). This check is not performed when the actual parameter is this ($e_i$ such that $i \in \mathcal{T}$) since no assumption about the nominal types of this can be made; instead the source language types used as types for this ($U_i$ for $i \in \mathcal{T}$) are included in the this-constraints collected in the conclusion of the rule. Then, the this-constraints and the trait-constraints imposed by the expressions involved in method invocation (the actual parameters $e_i$) are collected in the conclusion. Also the constraint that this must have a method $m$ with signature $\zeta$ is collected.

- Rule (T-INVKNONTHIS) checks method invocation when the receiver is not this is similar. First the signature of $m$ ($\mathcal{U}(m(U_1, \ldots, U_n))$ is extracted from by the type $\theta$ of the receiver $e_0$. Then, the types of the actual parameters $e_1, \ldots, e_n$ are checked. and the this-constraints and the trait-constraints imposed by the expressions involved in method invocation (the receiver $e_0$ and the actual parameters $e_1, \ldots, e_n$) are collected in the conclusion.

- Rule (T-NEW) for instance creation, is similar (but it uses the fields declared in the class to check the arguments of the constructor).

- Rule (T-REPL) checks the dynamic replacement $e\{T\}$. In the conclusion the trait-constraints are updated with $\{T < R\}$ since the trait $T$ is used for a dynamic replacement on $e$ of type $I\{R\}$.
Expression typing:

\[
\begin{align*}
\Gamma &\vdash x : \Gamma(x) + \{\bullet + \bullet + \bullet\} + \emptyset \quad \text{(T-VAR)} \\
\Gamma &\vdash \text{this} : \{F + \ldots\} + \{\bullet + \bullet + \bullet\} + \emptyset \quad \text{(T-FIELD)} \\
\Gamma &\vdash \text{this} : \{\ldots\} + \{\bullet + \bullet + \bullet\} + \emptyset \quad \forall i \in 1..n, \quad \Gamma &\vdash e_i : \theta_i + \{F(i) + \sigma(i) + \nabla(i)\} + \Delta(i) \\
\text{Um}(U_1,..,U_n) &\equiv \text{choose}(\sigma, m) = \zeta \\
\mathcal{T} &\equiv \{i | i \in 1..n \land \theta_i = \Gamma(\text{this})\} \quad \forall i \in 1..n - \mathcal{T}, \quad \theta_i <: U_i \\
\Gamma &\vdash \text{this}.m(e_1,\ldots,e_n) : U + \langle \cup_{i \in 1..n} F(i) + \zeta \cup (\cup_{i \in 1..n} \sigma(i)) \cup (\cup_{i \in 1..n} \nabla(i)) \cup (\cup_{i \in 1..n} \mathcal{T} \cup \mathcal{U}) \rangle + \cup_{i \in 1..n} \Delta(i) \\
\forall i \in 0..n, \quad \Gamma &\vdash e_i : \theta_i + \{F(i) + \sigma(i) + \nabla(i)\} + \Delta(i) \\
\text{Um}(U_1,..,U_n) &\equiv \text{choose}(mSig(\text{interfaces}(\theta)), m) \\
\mathcal{T} &\equiv \{i | i \in 1..n \land \theta_i = \Gamma(\text{this})\} \quad \forall i \in 1..n - \mathcal{T}, \quad \theta_i <: U_i \\
\Gamma &\vdash \text{new } C(e_1,\ldots,e_n) : C + \langle \cup_{i \in 1..n} F(i) + \cup_{i \in 0..n} \sigma(i) + (\cup_{i \in 1..n} \nabla(i)) \cup (\cup_{i \in 1..n} \mathcal{T} \cup \mathcal{U}) \rangle + \cup_{i \in 1..n} \Delta(i) \\
\Gamma &\vdash e : \{I(R)\} + \{F + \sigma + \nabla\} + \Delta \quad \text{trait } T \text{ is } \ldots \\
\Gamma &\vdash e(T) : \{I(R)\} + \{F + \sigma + \nabla\} + \Delta \cup \{T \in R\} \quad \text{(T-REPL)}
\end{align*}
\]

Method definition typing:

\[
\begin{align*}
\text{this} : \tau, \tau : \mathcal{S} - e : \theta + \{F + \sigma + \nabla\} + \Delta \\
\theta = \tau &\implies \cup^{\mathcal{S}} = \cup \cup \nabla \\
\theta \neq \tau &\implies (\theta <: \mathcal{V} \text{ and } \cup^{\mathcal{S}} = \mathcal{U}) \\
\text{this} : \tau &\vdash \mathcal{V}m(\mathcal{V}\mathcal{X}) + \{\text{return } e\} : \mathcal{V}m(\mathcal{V}) + \{F + \sigma + \nabla\} + \Delta \quad \text{(M-OK)}
\end{align*}
\]

Example 4.10. Consider the interface ISomeSequence in Listing 2, the trait TFifoPolicy in Listing 5, the replaceable RPolicy in Listing 9, and the trait replacement expression s[TFifoPolicy]. We have:

\[
\begin{align*}
\text{this} : \ldots, \mathcal{S}:\text{ISomeSequence}[\text{RPolicy}] &\vdash \mathcal{S}[\text{TFifoPolicy}] : \\
\text{ISomeSequence}[\text{RPolicy}] &\equiv \{\bullet + \bullet + \bullet\} + \{\text{TFifoPolicy} <\text{RPolicy}\}
\end{align*}
\]

Consider the interface ISomeSequence and the trait TExample2 in Listing 8, the replaceable RAnotherExample in Example 4.7, and the trait replacement expression x[TExample2]. We have:

\[
\begin{align*}
\text{this} : \ldots, x:\text{ISomeSequence}[\text{RAnotherExample}] &\vdash x[T\text{Example2}] : \\
\text{ISomeSequence}[\text{RAnotherExample}] &\equiv \{\bullet + \bullet + \bullet\} + \{T\text{Example2} <\text{RAnotherExample}\}
\end{align*}
\]

The typing rule judgement for method definitions is \[\text{this} : \tau - \mathcal{V}m(\mathcal{V}\mathcal{X}) + \{\text{return } e\} : \mu\], where \(\mu = \zeta + \gamma + \Delta\). To be read: “under the assumption that this has type \(\tau\), the definition of method \(m\) is well-typed with type \(\mu\).” That is, the method \(m\) has signature \(\zeta (= \mathcal{V}m(\mathcal{V}))\) and its body its body is type correct if the enclosing class satisfies the constraints \(\gamma\) and \(\Delta\). The associated rule, (M-OK), is given in Figure 5. There are two cases:

- If the type of the method body is \(\tau\) (i.e., the method simply returns this), then the sequence of source language types required for this is updated adding \(V\) (i.e., the return type of the method).
- Otherwise, the type of the body must be a subtype of the return type of the method.
 Trait expression typing:

\[
\begin{align*}
 mSig(\emptyset) &= \sigma \\
 mSig(M_1 \ldots M_p) &= \zeta_1 \ldots \zeta_p \\
 \forall i \in 1..p, \quad this : (F; \sigma; \zeta_1 \ldots \zeta_p) &\vdash M_i ; \mu_i \\
 \mu_i &= \zeta_i \triangleright \langle (F^{(i)}; \zeta^{(i)}); U^{(i)} \rangle \triangleright \Delta^{(i)} \\
 F &= F^{(1)} \cup \ldots \cup F^{(p)} \\
 \sigma &= \text{exclude}(\langle \zeta^{(1)} \cup \ldots \cup \zeta^{(p)} \rangle, \text{names}(\zeta_1 \ldots \zeta_p)) \\
 \forall \mathfrak{g} \supseteq F^{(1)} \cup \ldots \cup F^{(p)} \cup \text{fields}(U^{(1)}) \cup \ldots \cup \text{fields}(U^{(p)}) \\
 \zeta_1 \ldots \zeta_p &\supseteq \forall \mathfrak{g} \supseteq \forall \mathfrak{r} \cup \mu \cup mSig(U^{(1)}) \cup \ldots \cup mSig(U^{(p)}) \cup mSig(U) \\
 \forall \mathfrak{g} \in \forall \mathfrak{r}, \quad \exists I \subseteq I' \\
 \vdash \text{trait } T : \mu \\
 \vdash \text{trait } T \triangleright \text{TE} : \mu \\
 \\
 \vdash \text{class } C \text{ implements } \{ \forall \mathfrak{g} : C(\forall \mathfrak{g}) \{ \text{this.} \mathfrak{g} = \mathfrak{g} ; \} \} \quad \text{OK} \\
\end{align*}
\]  

(T-TEBASIC)

Figure 6: FDTJ typing rules for trait expressions, trait definitions and class definitions

The typing judgement for trait expressions is $\vdash \text{TE : } \mu$ where $\mu = \mu_1 \ldots \mu_n \quad (n \geq 0)$. To be read: “the trait expression TE is well-typed with type $\mu$”. That is, $\text{TE}$ provides $n$ methods with types $\mu_1, \ldots, \mu_n$, respectively. The associated rules, (T-TEBASIC) and (T-TENAME), are given in Figure 6.

- Rule (T-TEBASIC) checks that each method $M_i$ defined by the trait has a type $\mu_i$. The check is performed by assuming for this a type consisting of all the fields required by the trait ($F$) and of all the signatures of the methods required by the trait ($\sigma = mSig(\emptyset)$) and all the signatures of the methods defined by the trait ($\zeta_1 \ldots \zeta_p$). Then, it checks that all the methods together requires all the field requirements declared in the trait ($F = F^{(1)} \cup \ldots \cup F^{(p)}$), and that all the methods together requires all the method requirements declared in the trait ($\sigma = \text{exclude}(\langle \zeta^{(1)} \cup \ldots \cup \zeta^{(p)} \rangle, \text{names}(\zeta_1 \ldots \zeta_p))$). Finally, it checks that there are no conflicts among the fields/signatures declarations of the trait and the this-constraints inferred for the methods.

- Rule (T-TENAME) just assigns to the trait name $T$ the type inferred for the definition of the trait $T$.

The typing judgement for trait definitions is $\vdash \text{trait } T \triangleright \text{TE : } \mu$ to be read: “the definition of trait $T$ is well-typed with type $\mu$”. The associated rule, (T-OK), is given in Figure 6. It assigns to the the trait $T$ the type inferred for the trait expression $\text{TE}$ (remember that the trait reuse graph is acyclic).

Example 4.11. Consider the trait TEExample1 in Listing 8. Let

\[
\begin{align*}
 F &= \{ \text{ISSomeSequence } s; \text{ISSomeSequenceComparator } c; \} \\
 \sigma &= \text{sigmaOut } \sigma_{\text{isNotEmpty}} \sigma_{\text{outTwice}} \sigma_{\text{test}} \\
 M_{\text{outTwice}} &= M_{\text{isNotEmpty}} \\
 M_{\text{test}} &= \text{the signatures and the definitions of the provided methods, respectively; and let} \\
\end{align*}
\]  

be the required fields; let $\sigma_{\text{out}}$ and $\sigma_{\text{isNotEmpty}}$ be the signatures of the required methods; let $\sigma_{\text{outTwice}}$, $\sigma_{\text{isNotEmpty}}$, $\sigma_{\text{test}}$ and $M_{\text{outTwice}}$, $M_{\text{isNotEmpty}}$ and $M_{\text{test}}$ be the signature and the definitions of the provided methods, respectively; and let

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We have:

\[
\begin{align*}
\text{this} & : (\mathcal{F} : \mathcal{I}) \vdash M_{\text{outTwice}} : \mu_{\text{outTwice}} \\
\text{this} & : (\mathcal{F} : \mathcal{I}) \vdash M_{\text{isEmpty}} : \mu_{\text{isEmpty}} \\
\text{this} & : (\mathcal{F} : \mathcal{I}) \vdash M_{\text{test}} : \mu_{\text{test}} \\
\vdash & \text{TE}_{\text{Example}} : \mu_{\text{outTwice}} \mu_{\text{isEmpty}} \mu_{\text{test}}
\end{align*}
\]

where

\[
\begin{align*}
\mu_{\text{outTwice}} &= \sigma_{\text{outTwice}} = \{ \bullet \mapsto \text{void out()} : \bullet \} \cup \emptyset \\
\mu_{\text{isEmpty}} &= \sigma_{\text{isEmpty}} = \{ \bullet \mapsto \text{boolean isEmpty()} : \bullet \} \cup \emptyset \\
\mu_{\text{test}} &= \sigma_{\text{test}} = \{ \bullet \mapsto \text{ISomeSequence} : \bullet \} \cup \emptyset
\end{align*}
\]

The typing judgement for class definitions is \( \vdash \text{class C implements I} \text{ by TE} \{ \mathcal{F} ; \mathcal{K} \} \text{ OK} \) to be read: “the definition of the class C is well-typed”. The associated typing rule, \( (\text{C-Ok}) \), is given in Figure 6. It checks that the this-constraints inferred for the methods provided by the trait expression TE are satisfied. That is: that the class provides all the fields expected by the trait; that the trait provides all the methods that the class needs to correctly implement the interfaces I; and that, for each interface in the this-constraints of the trait, there is a subinterface implemented by the class.

4.2.5. Trait-Constraint Checking and Well-Typed Programs

In order to simplify the presentation of the trait-constraints checking rule and of the notion of well typed program we introduce the specificationof operation and the traitconstraintsof operation. Given a trait name \( T \): \( \text{specificationof}(T) \) returns a replaceable definition right-hand side that “characterizes” the set of methods defined by \( T \), and \( \text{traitconstraintsof}(T) \) returns the trait-constraints for the methods defined by \( T \). In the following definition we will use two lookup functions: fields (that given a source language type \( l[R] \) returns the sequence of the fields required by the replaceable R) and allInterfaces (that given \( l[R] \) returns the sequence formed by the interface name l and all the interfaces names listed in R) defined in Section 4.1.1.

**Definition 4.12.** Let \( \vdash T : \mu_1 \ldots \mu_p \) where (for all \( i \in 1 \ldots p \) ) \( \mu_i = \zeta_i : \{ \mathcal{F}_i : \mathcal{I}_i \} \), \( T \) returns the replaceable definition right-hand side that “characterizes” the set of methods defined by \( T \), and \( \text{traitconstraintsof}(T) \) returns the trait-constraints for the methods defined by \( T \). In the following definition we will use two lookup functions: fields (that given a source language type \( l[R] \) returns the sequence of the fields required by the replaceable R) and allInterfaces (that given \( l[R] \) returns the sequence formed by the interface name l and all the interfaces names listed in R) defined in Section 4.1.1.

**Definition 4.12.** Let \( \vdash T : \mu_1 \ldots \mu_p \) where (for all \( i \in 1 \ldots p \) ) \( \mu_i = \zeta_i : \{ \mathcal{F}_i : \mathcal{I}_i \} \),

1. We define \( \text{specificationof}(T) \) as \( \{ \zeta ; \{ \mathcal{F}_i : \mathcal{I}_i \} \} \), where \( \zeta = \zeta_1 \ldots \zeta_p \), \( \mathcal{F} = (\cup_{i \in 1 \ldots p} \mathcal{F}_i) \cup (\cup_{i \in 1 \ldots p} \text{fields}(\mathcal{I}_i)) \), \( \mathcal{I} = \text{allInterfaces}(\cup_{i \in 1 \ldots p} \mathcal{I}_i) \).

2. We define \( \text{traitconstraintsof}(T) \) as \( \cup_{i \in 1 \ldots p} \Delta \).

Observe that, while the specificationof operation for classes (in Definition 4.3) does not rely on the typing rules, the value of \( \text{specificationof}(T) \) and \( \text{traitconstraintsof}(T) \) can be computed only when the typing of the trait \( T \) is available.

**Example 4.13.** Consider the replaceable RExample and the trait TEExample1 in Listing 8. We have that \( \text{specificationof}(\text{TEExample1}) \) yields the left-hand side of the definition of the replaceable RExample.

**Convention 4.14.** For every trait \( T \), we write \( R_T \) to denote a distinguished replaceable name (that cannot occur in source programs) and assume the replaceable definition \( \text{replaceable R}_T \) is specificationof(T).

The following proposition illustrates the meaning of Definition 4.12 and Convention 4.14 in terms of Definition 4.6 (the proof is straightforward).

**Proposition 4.15.** For every trait \( T \), if \( M \) is the set of methods of \( T \), then \( M \) satisfies \( R_T \).

The judgement for trait-constraint checking is \( \vdash T \sqsubseteq R \text{ OK} \) to be read: “the constraint \( T \sqsubseteq R \) is satisfied”. The associated typing rule, \( (\sqsubseteq\text{-Ok}) \), is given in Figure 7. The rule exploits Definition 4.12 and Convention 4.14. It checks that the trait \( T \) can actually replace the methods specified in the replaceable \( R \) by relying on the replaceable inclusion relation of Figure 3.

**Definition 4.16 (Well-typed FDTJ programs).** We write \( \vdash_{\text{FDTJ}} (\text{IT}, \text{TT}, \text{RT}, \text{CT}, e) : \pi \), to be read: “the program \( (\text{IT}, \text{TT}, \text{RT}, \text{CT}, e) \) is well-typed with type \( \pi \)”, to mean that
4.3. Reduction

Dynamic trait replacement is an imperative operation working on a per-object basis. That is, while the methods associated to the object’s class remain unchanged, the object must keep track of the methods that have been introduced by means of dynamic replacements.

In order to model object identities and dynamic replacements we need to model the notions of address, object and heap. Addresses, ranged over by the metavariable $\iota$, are the elements of the denumerable set $\mathbb{I}$. An object is a triple $\langle C, \tilde{T}, \tilde{M} \rangle$, where $C$ is the object’s class, $\tilde{T}$ is a mapping from the names of the object’s fields to their values (i.e., addresses) and $\tilde{M}$ are the object’s methods that have been introduced by means of dynamic replacements (therefore, immediately after object creation this set will be empty). A heap, $\mathcal{H}$, is a mapping from addresses to objects. The empty heap will be denoted by $/ 0$.

The states of a computation are represented by means of configurations. A configuration is a pair “$e, \mathcal{H}$”, where $e$ is a runtime expression (i.e., the code under evaluation) and $\mathcal{H}$ is a heap. Runtime expressions, ranged over by $e$, are obtained from source language expressions by removing variables and adding values (i.e., addresses).

The reduction relation has the form $e, \mathcal{H} \longrightarrow e', \mathcal{H}'$, read “configuration $e, \mathcal{H}$ reduces to configuration $e', \mathcal{H}'$ in one step”. We write $\longrightarrow^*$ for the reflexive and transitive closure of $\longrightarrow$. The reduction rules, given in Figure 8, ensure that the computation is carried on according to a call-by-value reduction strategy by using the standard notions of computation rules and congruence rules.

The most interesting rules are the computation rules. The rule for field selection, (R-FIELD), returns the value associated to the selected field. The rule for object creation, (R-NEW), stores the newly created object at a fresh address of the heap and returns the address. Object’s fields are initialized as specified by the class constructor. The rule for method invocation, (R-INVK), searches for the method definition for $m$ in the set of replaced methods $\tilde{M}$, and if it cannot find it then it relies on the method definition that is found in the original object (exclude(methods($C$), names($\tilde{M}$))) $\cup \tilde{M}$). Note that this lookup will always succeed in a well-typed program. Rule (R-REPL) performs method replacement: since replacements can be performed many times on an object, we must take care of removing methods that were previously replaced.

5. Properties

The type soundness result for the FDTJ calculus is as follows.

**Theorem 5.1 (FDTJ Type Soundness).** Let $\vdash e_0 : \pi \downarrow \{ \mathbb{\cdot} \mathbb{\cdot} \mathbb{\cdot} \} \downarrow \Delta$ and $\vdash \delta$ OK for all $\delta \in \Delta$. If $e_0, \emptyset \longrightarrow^* e, \mathcal{H}$ with $e$ a normal form, then the heap $\mathcal{H}$ is well formed and $e$ is an address $\iota$ such that $\mathcal{H}(\iota) = \langle C, \mathbb{\cdot} \mathbb{\cdot} \mathbb{\cdot} \rangle$ and $C < : \pi$. 

\[ \vdash \text{trait } T \text{ is } \forall \mu_1 \ldots \mu_p \vdash \text{trait } R \text{ is } \{ \mathbb{\cdot} \mathbb{\cdot} \mathbb{\cdot} \}\langle \mathbb{G}, \mathbb{\cdot} \rangle ; \mathbb{J} \rangle \vdash T \ll R \quad \text{OK} \quad \text{(<\cdot Ok)} \]

Figure 7: FDTJ checking rule for trait-constraints

- the interfaces in $\mathbf{IT}$, the replaceables in $\mathbf{RT}$, the traits in $\mathbf{TT}$ and the classes in $\mathbf{CT}$ are well-typed,

- all the trait-constraints for the methods defined by the traits in $\mathbf{TT}$ are satisfied (that is, for all trait $T$ in $\mathbf{TT}$ and for all $\delta$ in traitconstraints of $T$ the judgement $\vdash \delta$ OK holds), and

- the expression $e$ is well typed with type $\pi$, empty this-constraints and some satisfied trait-constraints $\Delta$, under the empty set of assumptions (that is, the judgment $\vdash e : \pi \downarrow \{ \mathbb{\cdot} \mathbb{\cdot} \mathbb{\cdot} \} \downarrow \Delta$ holds and, for all $\delta \in \Delta$, the judgment $\vdash \delta$ OK holds).

Note that the expression to be executed, $e$, is closed (that is, it does not contain variables).
Computation rules:

\[
H(t) = \langle C, \ldots, f_i : t_i, \ldots, M \rangle
\]

(\text{R-FIELD})

\[
H(t) = \langle C, f : T, M \rangle \cup \{ m \mid \text{return } e \} \in \text{exclude}(\text{methods}(C), \text{names}(M)) \cup M
\]

(\text{R-INVK})

\[
t \notin \text{Dom}(H), \quad \text{fields}(C) = F \quad \text{new } C(T), H \rightarrow t, H \cup \{ t \mapsto \langle C, f : T, \star \} \}
\]

(\text{R-NEW})

\[
H(t) = \langle C, f : T, M \rangle, \quad \text{methods}(T) = M
\]

(\text{R-REPL})

Congruence rules:

\[
e \cdot H \rightarrow e' \cdot H', \quad e \cdot \{ T \}, H \rightarrow e' \cdot \{ T \}, H', \quad e \cdot m(\pi), H \rightarrow e' \cdot m(\pi), H'
\]

\[
t_0 \cdot m(\pi, e_1, \pi), H \rightarrow t_0 \cdot m(\pi, e_1', \pi), H', \quad \text{new } C(\{ e_1, \pi \}, H) \rightarrow \text{new } C(\{ e_1', \pi \}, H')
\]

Figure 8: FDTJ reduction rules

To prove the type soundness result we will introduce a suitable notion of typing for configurations (that is, runtime expressions and heaps). The objects in the heap may contain methods introduced by means of dynamic replacement, which encompass both source language expressions and runtime expressions. This notion of open runtime expressions allows us to simplify the structure of the proof of the properties that relate source language typing with runtime typing. In particular, it makes it possible to relate the source language typing of a method to the runtime typing of its method body and then to rely on the substitution lemma for open runtime expression typing (Lemma A.3 in the appendix).

A runtime type environment \( \Sigma \) is a finite (possibly empty) mapping that: either (i) maps addresses to class names; or (ii) maps this to a class name and maps variable names (different from this) to source language types (that are types of the form \( I \)).

The typing judgement for (runtime or source language) expressions is \( \Sigma \vdash e : \pi \) to be read “under the assumptions in \( \Sigma \), the (runtime or source language) expression \( e \) is well-typed with type \( \pi \)”. Note that the conclusion of the typing judgement does not contain constraints (as we will see, in order to prove the type soundness result, it is not necessary to infer constraints on runtime expressions or on methods introduced by means of dynamic replacement).

The associated typing rules, given at the top of Figure 9, make use of the subtyping judgement \( \pi_1 < : \pi_2 \) introduced in Section 4 (Figure 3). As for the typing rules for source language expressions (in Figure 5) also the typing rules for runtime expressions are syntax directed, with one rule for each form of expression. Note that, in rule (RT-FIELD), the expression \( e \) can be either \( \text{this} \) or \( t \) (this is enforced by the first premise of the rule). The most interesting rule is the one for dynamic trait replacement, (RT-REPL). It relies on the fact that, if the runtime expression \( e \{ T \} \) has been generated starting from a well-typed program (see Definition 4.16), then the type inferred for \( e \) must be a subtype of some source program type \( I \{ R \} \) such that the validity of the judgement \( \vdash T < R \) OK has been already established (at compile-time) when typing the source program (see Theorem 5.2).

The judgment for well formed heap has the form \( \Sigma \vdash H \), read “heap \( H \) is well formed with respect to the environment \( \Sigma \)”. The associated rule, given at the bottom of Figure 9, ensures that the environment \( \Sigma \) maps all the addresses defined in the heap into the type of the corresponding objects. It also ensures that, for every object stored in the heap, the fields of the object contain appropriate values and the methods of the object introduced by dynamic
Open runtime expression typing:

\[ \Sigma \vdash x : \Sigma(x) \hspace{1cm} \text{(RT-VAR)} \]

\[ \Sigma \vdash t : \Sigma(t) \hspace{1cm} \text{(RT-ADDR)} \]

\[ \Sigma \vdash e : C \hspace{1cm} \text{fields}(C) = F \hspace{1cm} \forall f \in F \hspace{1cm} \text{(RT-FIELD)} \]

\[ \Sigma \vdash e : \pi \hspace{1cm} \forall i \in 1..n, \hspace{1cm} \Sigma \vdash e_i : \pi_i \hspace{1cm} \pi_i <: \pi_i \hspace{1cm} \text{(RT-INVK)} \]

\[ \Sigma \vdash e.m(e_1, ..., e_n) : U \hspace{1cm} \text{(RT-NEW)} \]

Well-formed heap:

\[ \text{Dom}(\mathcal{H}) = \text{Dom}(\Sigma) \]

\[ \forall t \in \text{Dom}(\mathcal{H}), \hspace{0.5cm} \mathcal{H}(t) = (C, \ f_1 : t_1, ..., \ f_n : t_n, \ M) \implies \]

\[ \Sigma(t) = C \hspace{1cm} \text{fields}(C) = U_1 f_1; ...; U_n f_n; \]

\[ \forall i \in 1..n, \hspace{1cm} \Sigma(t_i) <: U_i \]

\[ mSig(M) \subseteq mSig(C) \]

\[ \forall \Sigma \exists \forall \mathcal{M} \hspace{0.5cm} \text{if } e \in \mathcal{M}, \hspace{1cm} \exists \forall' \hspace{1cm} \text{this } : C, \pi : \forall' \vdash e : \forall', \forall' <: \forall \hspace{1cm} \text{(WF-HEAP)} \]

Figure 9: FDTJ: Typing rules for runtime expressions and heaps

replacements are well-typed.

The FDTJ type soundness result (Theorem 5.1) comes in two parts: first the notion of well-typed program (see Definition 4.16) is related with the typing of runtime expressions (Theorem 5.2), then the type soundness for runtime expressions is given (Theorem 5.5). Theorem 5.2 can be proved by straightforward induction on the type derivation, while Theorem 5.5 follows immediately from subject reduction and progress (Theorems 5.3 and 5.4 — the proofs are given in Appendix A).

**Theorem 5.2 (\vdash -typed closed expressions are \vdash -typed).** If \( \Sigma \vdash e : \pi \), then \( \bullet \vdash e : \pi \).

**Theorem 5.3 (Subject reduction).** If \( \Sigma \vdash \mathcal{H}, \Sigma \vdash e : \pi \) and \( e, \mathcal{H} \rightarrow e', \mathcal{H}' \), then there exists \( \Sigma' \supseteq \Sigma \) such that \( \Sigma' \vdash \mathcal{H}', \Sigma' \vdash e' : \pi' \), for some \( \pi' \) such that \( \pi' <: \pi \).

**Theorem 5.4 (Progress).** Let \( \Sigma \vdash \mathcal{H} \) and \( \Sigma \vdash e : \pi \), where \( e \) is a runtime expression. Then either \( e \) is a value or there exist \( e' \) and \( \mathcal{H}' \) such that \( e, \mathcal{H} \rightarrow e', \mathcal{H}' \).

**Theorem 5.5 (Type Soundness).** If \( \Sigma \vdash \mathcal{H}, \Sigma \vdash e : \pi \), then \( e \) is a normal form, then \( e \) is an address \( t \) and there exist \( \Sigma \) and \( C \) such that \( \Sigma \vdash \mathcal{H}', \Sigma \vdash t : C \) and \( C <: \pi \).

6. Related Work

Some of the literature related to traits and dynamic trait replacement has already been quoted through the paper. Here we present a more detailed comparison between FDTJ and Chai, and briefly discuss some other languages.
and calculi that provide mechanisms similar to trait replacement or type systems that integrate nominal and structural subtyping.

The language Chai$_3$ [36] does not have interfaces and therefore does not consider the issue of performing dynamic trait replacement when the static type of the target expression is an interface, that we have addressed by introducing types of the shape I[R]. The trait replacement operation of Chai$_3$ must be applied to expressions whose static type is a class. The trait to be replaced must correspond to a trait T that was used in the class implementation and to replace a trait in an object it is necessary to specify such name. In particular, it is not possible to write a trait replacement operation that replaces a proper subset of the methods of T. For instance, the trait replacement operations (1), (2), (3) and (4) in Section 3.2 cannot be written in Chai$_3$ since each of them replaces a proper subset of the methods in the trait TFifo used in the definition of the class Sequence in Listing 4. In some cases, the replacement of a proper subset of the methods of a trait used in the definition of a class can be encoded by replacing more methods. For instance, let TLo be the trait obtained from TLoExtractionPolicy by adding the methods in and isEmpty of trait TFifo, then the following Chai$_3$ method changePolicy2 would behave like the method changePolicy1 in Section 3.3

```java
void changePolicy2(Sequence s) {
    s<TFifo -> TLo>;  // (1'')
    System.out.println(s.get());
    s.out();
    s<TFifo -> TFifo> // (2'')
}
```

However, while the method changePolicy1 in Section 3.3 works for both the versions of the class Sequence in Listings 4 and 7, the Chai$_3$ method changePolicy2 works only for the versions of the class Sequence in Listing 4. In fact, in Chai$_3$, when replacing a trait in an object it is necessary to specify the name of the trait used in the object’s class definition. Therefore, modifying a class definition by changing the name of one of the traits used in the class implementation invalidates all the trait replacement operations associated to the changed trait. For instance, if the class Sequence in Listing 4 is changed as in Listing 7, so that it uses trait TLIfo (i.e., sequences would be created as Last-in-first-out sequences), the code for the trait replacement operations (1') and (2') above should be changed into s<TLifo -> TLo> and s<TLifo -> TFifo>, respectively. Moreover, by replacing more methods, it is not possible to encode the methods disableIn and enableIn of Section 3.2 that accept as argument a sequence object and disable/enable the method in without affecting the methods out and get. In order to encode the methods disableIn and enableIn into Chai$_3$, it is needed to consider a different strategy of encoding: for instance, by rewriting all the traits to contain just one provided method each, and then by expressing all the dynamic updates one method at time.

Dynamic method replacement is a basic feature of the Abadi-Cardelli imperative object calculus [1], a formalism aiming to encode (as many as possible) features of object-oriented languages. In this paper we have a different aim, that is, to formalize dynamic method replacement within a JAVA-like nominal type system in order to foster its adoption in mainstream programming languages.

Recently, Zdara [39] used the phrase “dynamic traits” to term a language feature where the schema of dependence between objects and traits is reversed with respect to our proposal, namely, traits are dynamically bound to object references to provide different views to the same object.

The idea of changing the behavior of objects at runtime has been investigated in several ways in the literature. In [23] an extension of JAVA-like languages with delegation is proposed, thus extending object behaviors by forwarding messages to objects with a different type/interface. To this aim classes defining delegator objects usually have an explicit reference to the delegate object as in the State pattern.

In [15] a dynamic inheritance mechanism for dynamic specialization of objects, is presented for the GBETA language. The proposed mechanism is quite flexible, however it is not type safe. Moreover, it relies on the submethoding feature supported by BETA, therefore its integration into JAVA-like language would first require the integration of the submethoding feature.

Primitives for changing at runtime the class membership of an object are present, for instance, in the dynamic languages SMALLTALK and CLOS. The paper [13] presents, through the Fickle$_4$ language features for changing at runtime the class membership of an object within a JAVA-like nominal type system. In Fickle$_4$ only objects belonging to special classes, called root and state classes, can be reclassified and the type system restricts the use of these classes. This makes the flexibility/expressivity of Fickle$_4$ similar to the one of Chai$_3$ [36]. We refer to [13] for a
brief overview of approaches related to dynamic object reclassification. The Fickle calculus \[12\] eliminates the need to declare explicitly which are the classes of the objects that may be re-classified. Re-classification may be decided by the client of a class, allowing unanticipated object re-classification. Still, the type system restricts the use of the classes of the objects that may be re-classified.

In context of dynamically typed languages, a very high degree of flexibility can be achieved by combining the prototype based approach with multiple dispatch \[34\].

More recently, in \[4, 5\] an extension of FJ with object composition and delegation is presented. In that calculus methods can be changed dynamically at runtime on an existing object as a consequence of object composition and “redefining” methods (a runtime version of standard method overriding). However, the objects that may be composed must be instance of special classes, thus, the structure of classes and special classes must be designed in advance, while FDTJ supports unanticipated method substitutions.

The FDTJ type system has a flavor of both structural and nominal systems. Integration of nominal and structural subtyping has recently received a considerable deal of interest (see, e.g., \[27, 19, 30\]). The shape of FDTJ source language types, \(\{R\}\), is similar to the shape of the types of Unity \[27\], \(\beta(m:\tau)\) where \(\beta\) is a brand name and \(m:\tau\) is a sequence of method signatures. However, there are crucial differences. Brands are closer to JAVA classes rather than to JAVA interfaces: a brand declaration may contain the code of methods and the sub-branding inheritance hierarchy must be a tree. Moreover, Unity does not address issues of implementation inheritance, while traits provide a solution to these issues, and Unity (which is a pure functional calculus) is not able to (and does not aim to) express dynamic method replacement.

7. Conclusion and Future Work

We proposed statically typed language features that decouple trait replacement operation code and class declaration code. These features support to refactor classes and/or performing unanticipated trait replacement operations without invalidating existing code. We illustrated these features through examples and proved the soundness of the associated typing rule by means of the FDTJ calculus.

Further work includes developing a prototypical implementation and validating the usability of the approach through examples. A possible implementation could consist in a preprocessor that generates JAVA code that relies on JAVA reflection, for selecting dynamically the replaced methods. Note that reflection might also be used to achieve method replacement manually, but in that case, type safety could not be checked statically.

We are also planning to strengthen the integration between nominal and structural subtyping and to add generics. Finally, it could be interesting to investigate method replacement in connection with classes/methods having invariants/contracts.

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References

Lemma A.2 (Weakening).

Remember that the rules for system $\Sigma \vdash \cdot$ are syntax directed.

In order to prove Theorem 5.3 we first prove some auxiliary lemmas: Lemma A.2 (weakening), Lemma A.3 (substitution), Lemmas A.4 and A.5 (used to deal with method invocation) and Lemmas A.6 and A.7 (used to deal with trait replacement).

**Lemma A.2 (Weakening).** \( \text{If } \Sigma \vdash t : \pi, \text{ then } \Sigma, t : \Theta \vdash t : \pi \).  

**Proof.** Straightforward induction on the derivation of $\Sigma \vdash t : \pi$.  

A. Proofs of Theorems 5.3 and 5.4

**Definition A.1.** We define the following auxiliary functions on trait expressions:

\[
\begin{align*}
\text{mRequired}(T) &= \text{mRequired}(\text{TE}) \text{ if } T \text{ is } TE \\
\text{mRequired}([\ldots; \Theta; \ldots]) &= \Theta \\
\text{fRequired}(T) &= \text{fRequired}(\text{TE}) \text{ if } T \text{ is } TE \\
\text{fRequired}([\overline{F}; \ldots; \overline{F}]) &= \overline{F}
\end{align*}
\]

A.1. Proof of Theorem 5.3

Remember that the rules for system $\Sigma \vdash \cdot$ (Figure 9) are syntax directed.

In order to prove Theorem 5.3 we first prove some auxiliary lemmas: Lemma A.2 (weakening), Lemma A.3 (substitution), Lemmas A.4 and A.5 (used to deal with method invocation) and Lemmas A.6 and A.7 (used to deal with trait replacement).

**Lemma A.2 (Weakening).** \( \text{If } \Sigma \vdash t : \pi, \text{ then } \Sigma, t : \Theta \vdash t : \pi \).  

**Proof.** Straightforward induction on the derivation of $\Sigma \vdash t : \pi$.  

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Lemma A.3 (Substitution). If $\Sigma, \overline{x} : \pi \vdash e : \pi$ and $\Sigma \vdash \forall \overline{v} : \overline{C},$ where $\overline{G} : \pi$, then $\Sigma \vdash e[\overline{y}/\overline{x}] : \pi', \text{ for some } \pi' : \pi.$

**Proof.** By induction on the derivation of $\Sigma, \overline{x} : \pi \vdash e : \pi$. We show only the most interesting cases.

**Case $e_0, m(\overline{r}).$** Then $\Sigma, \overline{x} : \pi \vdash e_0, m(\overline{r}) : \pi$, where $\pi = U$, and

$\Sigma \vdash e_0 : \pi'_0, \forall i \in 1..n, \Sigma \vdash e_i : \pi'_i, \pi'_i : U_i,$

$U \Gamma (U_1, \ldots, U_n) = \text{choose}(m \Sigma(\pi'_0), m)$

for some $U, \pi'_0, \pi'_1, \ldots, \pi'_n, U_1, \ldots, U_n$. By induction we have $\forall i \in 0..n, \Sigma \vdash e_i[\overline{y}/\overline{x}] : \pi''_i$ for some $\pi''_i$ such that $\pi''_i : \pi'_i$. By the subtyping relation, $m \Sigma(\pi'_0) \subseteq m \Sigma(\pi''_0)$. Therefore, $U \Gamma (U_1, \ldots, U_n) \in \text{choose}(m \Sigma(\pi''_0), m)$.

Applying rule (RT-INVK) we get $\Sigma \vdash e[\overline{y}/\overline{x}] : \pi$ which proves the result.

**Case new $C(\overline{r}).$** Similar to the previous one.

**Case $e_0\{T\}.$** Then $\Sigma \vdash e_0\{T\} : \pi$ and

$\Sigma \vdash e_0 : \pi, \exists! l \{R\}, \pi : l \{R\} \vdash T \Rightarrow R \text{ OK}$

By induction $\Sigma \vdash e[\overline{y}/\overline{x}] : \pi'$ for some $\pi'$ such that $\pi' : \pi$ and by transitivity $\pi' : \pi : l \{R\}$. Applying rule (RT-REPL) we get $\Sigma \vdash e[\overline{y}/\overline{x}] : \pi'$ which proves the result. □

**Lemma A.4.** If

- $\vdash \text{class } C \text{ implements } \Gamma \text{ by } \{ \forall \overline{g}, C(\forall \overline{g}) \{\ldots\} \}$ OK
- $f \text{Required}(\Gamma) = F$ and methods(\Gamma) = $\overline{M}$
- $\exists \overline{x} : (F : m \Sigma(\overline{M}) \}, \overline{x} : U \vdash e : \theta : \gamma : \Delta$

then this: $C, \overline{x} : U \vdash e : \pi$ for some $\pi$ such that:

if $\theta = (F : m \Sigma(\overline{M}) \}$ then $\pi = C$, else $\pi : \theta$.

**Proof.** Assume (without loss of generality) that $\Gamma$ is a basic trait expression. By rules (C-OK) and (T-TEBASIC) we have $m \text{Required}(\Gamma) = \bullet$. Then the result follows by straightforward induction on the derivation $\exists \overline{x} : (F : m \Sigma(\overline{M}) \}, \overline{x} : U \vdash e : \theta : \gamma : \Delta$. □

**Lemma A.5.** If

- $\vdash \text{class } C \text{ implements } \Gamma \text{ by } \{ \forall \overline{g}, C(\forall \overline{g}) \{\ldots\} \}$ OK
- $W m (\overline{M} \overline{x}) \{\text{return } e;\} \in \text{methods}(\Gamma)$

then this: $C, \overline{x} : W \vdash e : \pi$ for some $\pi$ such that $\pi : W$.

**Proof.** Assume (without loss of generality) that $\Gamma$ is a basic trait expression $\{F, \Sigma, \overline{M}\}$ then methods(\Gamma) = $\overline{M}$. By rules (C-OK) and (T-TEBASIC) we have $\overline{S} = \bullet$. From hypothesis and rule (C-OK) we have

\[
\begin{align*}
\vdash \{F, \bullet, \overline{M}\} : & \mu_1 \ldots \mu_p, p \geq 0 \\
& \forall i \in 1..p, \mu_i = \zeta_i \vdash \{F(i), \overline{\sigma}(i), \overline{U}(i)\} \vdash \Delta(i) \\
\forall \overline{v} \subseteq (U_{i \in 1..p}\overline{F}(i)) \cup (U_{i \in 1..p}\text{fields}(\overline{U}(i))) & \vdash \zeta_1 \ldots \zeta_p \vdash (U_{i \in 1..p}\overline{\sigma}(i)) \cup (U_{i \in 1..p}\text{mSig}(\overline{U}(i))) \cup m \Sigma(\overline{I}) \quad (***) \\
& \forall \overline{i} \in U_{i \in 1..p}\text{allInterfaces}(\overline{U}(i)), \forall i \in \overline{I}, \overline{i} \leq \overline{i}' \quad (***)
\end{align*}
\]
Lemma A.6. If

\[ \vdash \text{class } C \text{ implements } \iota \text{ by } \text{TE} \{ \bar{V} \bar{g}; C(\bar{V} \bar{g}) \{ \ldots \} \} \text{ OK} \]

\[ \vdash \text{trait } T \text{ is } \text{TE}' : \pi \]

\[ \exists I(R), \quad C :<: I(R) \vdash R : \text{OK} \]

\[ f(\text{Required}(T) = F, m(\text{Required}(T) = S \text{ and methods}(T) = M) \]

\[ \text{this} : \langle F : m(\text{Sig}(M)) \cup \text{Sig}(S) \rangle, \bar{x} : U \vdash e : \theta \uparrow \gamma \uparrow \Delta \]

then this : \[ C, \bar{x} : U \vdash e : \pi \text{ for some } \pi \text{ such that:} \]

if \[ \theta = \langle F : m(\text{Sig}(M)) \cup \text{Sig}(S) \rangle \text{ then } \pi = C, \text{ else } \pi :<: \theta. \]

PROOF. By straightforward induction on the derivation
this : \[ F : m(\text{Sig}(M)) \cup \text{Sig}(S) \}, \bar{x} : U \vdash e : \theta \uparrow \gamma \uparrow \Delta. \]

Lemma A.7. If

\[ \vdash \text{class } C \text{ implements } \iota \text{ by } \text{TE} \{ \bar{V} \bar{g}; C(\bar{V} \bar{g}) \{ \ldots \} \} \text{ OK} \]

\[ \vdash \text{trait } T \text{ is } \text{TE}' : \pi \]

\[ \exists I(R), \quad C :<: I(R) \vdash R : \text{OK} \]

\[ W \vdash \text{m}(W \chi) \{ \text{return e; } \} \in \text{methods}(T) \]

then this : \[ C, \bar{x} : W \vdash e : \pi \text{ for some } \pi \text{ such that } \pi :<: \theta. \]

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PROOF. Assume (without loss of generality) that $TE$ is a basic trait expression $\{ F; S; M \}$. By rules (C-OK) and (T-TEBASIC) we have $S = \bullet$. From hypothesis and rule (C-OK) we have

$$\vdash \{ F; \bullet; M \} : \mu_1 ... \mu_p \quad p \geq 0$$

$$\forall i \in 1..p, \quad \mu_i = \zeta_i \vdash \{ F^{(i)}; \sigma^{(i)}; \bar{U}^{(i)} \} : \Delta^{(i)}$$

$$\forall g \supseteq (\cup_{i \leq 1..p} F^{(i)}) \cup (\cup_{i \leq 1..p} \text{fields}(U^{(i)}))$$

$$\zeta_1 ... \zeta_p \supseteq (\cup_{i \leq 1..p} \sigma^{(i)}) \cup (\cup_{i \leq 1..p} \text{mSig}(U^{(i)})) \cup \text{mSig}(\bar{U})$$

$$\forall \bar{W} \in \cup_{i \leq 1..p} \text{allInterfaces}(U^{(i)}), \quad \exists i \in 1, \quad 1 \leq i'$$

Assume (without loss of generality) that $TE'$ is a basic trait expression $\{ F'; S'; M' \}$. From rule (T-TEBASIC) we have

$$\text{mSig}(S') = \sigma' \quad \text{mSig}(M'_1 ... M'_{p'}) = \zeta'_1 ... \zeta'_{p'} \quad p' \geq 0$$

$$\forall i \in 1..p' \text{ this: } \langle F'; \sigma'; \zeta'_1 ... \zeta'_{p'} \rangle \vdash W \text{ m } (\bar{W} \bar{x}) \{ \text{return e: } \} : \mu'_i$$

$$\mu_i = \zeta'_j \vdash \{ F^{(i)}; \sigma^{(i)}; \bar{U}^{(i)} \} : \Delta^{(i)}$$

Let $\zeta'_j = W \text{ m } (\bar{W})$ for some $j \in 1..p'$. From rule (M-OK) we have

$$\text{this: } \langle F'; \sigma'; \zeta'_1 ... \zeta'_{p'} \rangle, \bar{x} : W \vdash e : \theta \vdash \{ F^{(i)}; \sigma^{(i)}; \bar{U}^{(i)} \} : \Delta^{(i)}$$

where:

- If $\theta = \langle F'; \sigma'; \zeta'_1 ... \zeta'_{p'} \rangle$ then $\bar{U}^{(i)} = \bar{U}^{(i)} \cup W$. By Lemma A.6, we have this: $C, \bar{x} : \bar{W} \vdash e : C$. Let $W = I_0 (R_0)$. By definition of $RT$ we have $R_0 \subseteq RT$. From $\vdash T < R$ OK by rule ($<$-OK) we have $R_T \subseteq R$. Therefore by definition of $RT$ we also have $R_0 \subseteq R_C$. Then:

  - By transitivity we have $R_T \subseteq R_C$ and since $I_0 \in RT$ by replaceable inclusion rule we have $\exists I \in I : I \subseteq I_0$

  - By transitivity we also have $R_0 \subseteq R_C$

Then by Lemma A.6, we have this: $C, \bar{x} : \bar{W} \vdash e : \pi$ with $\pi <: \theta <: W$.

\[ \square \]

**Proof of Theorem 5.3 (Subject Reduction).** The proof is by induction on a derivation of $e, \mathcal{H} \longrightarrow e', \mathcal{H}'$, with a case analysis on the reduction rule used. We show only the most interesting cases for computation rules; for congruence rules simply use the induction hypothesis.

**Case (R-INVK).** The last applied rule is

$$t.m(T), \mathcal{H} \longrightarrow e[t/this, T/x], \mathcal{H}$$

where $\mathcal{H}(t) = \langle C, T, M \rangle$ and $\cup m (\bar{W} \bar{x}) \{ \text{return e: } \} \in \text{exclude}(C, \text{names}(M)) \cup \bar{M}$. From rule (RT-INVK) we have

$$\Sigma \vdash t : C', \forall i \in 1..n, \quad \Sigma \vdash u_i : C_i \quad C_i <: U_i$$

$$\cup m (U_1, ..., U_n) = \text{choose}(\text{mSig}(C'), m)$$

where $\Sigma \vdash \mathcal{H}$ implies $C' = C$. There are two cases:

1. $\forall \bar{W} \bar{x} \{ \text{return e: } \} \in \bar{M}$ then from $\Sigma \vdash \mathcal{H}$ we have $\text{mSig}(\bar{M}) \subseteq \text{mSig}(C)$ thus $\forall = U, \bar{W} = \bar{U},$ this : $C, \bar{x} : U \vdash e : V'$ and $\forall' <: U$. Therefore, by Lemma A.3 and A.2, we have that $\Sigma \vdash e[t/this, T/x] : \pi$, where $\pi <: \forall' <: U$ which proves the result.

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2. \( \text{U m } (\overline{U} \overline{x})\{ \text{return } e; \} \in \text{methods}(C) \). Since class \( C \) is well-formed, then method \( m \) is well-typed and then, from Lemma A.5, we have that this : \( C, \overline{x} : U \vdash e : \pi \), where \( \pi <: U \). Therefore, by Lemma A.3 and A.2, we have that \( \Sigma \vdash ' e \left[ /\theta, \Gamma / \overline{x} \right] : \pi' \), where \( \pi' <: \pi <: U \).

**Case (R-NEW).** We have that

\[
\text{new } C(T), \mathcal{H} \longrightarrow \tau, \mathcal{H} \cup \{ \tau \rightarrow (C, \tilde{f} : \tau, \bullet) \},
\]

where \( \tau \notin \text{Dom}(\mathcal{H}) \). From rule (RT-NEW) we have

\[
\text{fields}(C) = U_1 f_1, \ldots, U_n f_n; \quad \forall i \in 1 \ldots n, \Sigma \vdash f_i : \pi_i \quad \pi_i <: U_i
\]

Let \( \Sigma' \) be such that \( \Sigma' = \Sigma \cup \{ \tau : C \} \). Then \( \Sigma \vdash \tau : C \) and \( \Sigma' \vdash \mathcal{H}' \), where \( \mathcal{H}' = \mathcal{H} \cup \{ \tau \rightarrow (C, \tilde{f} : \tau, \bullet) \} \).

**Case (R-REPL).** We have that

\[
\tau \{ T \}, \mathcal{H} \longrightarrow \tau, \mathcal{H}[\tau \rightarrow (C, \tilde{f} : \tau, \text{exclude}(\overline{M}, \text{names}(\overline{M})) \cup \overline{M}']]
\]

where \( \mathcal{H}(t) = (C, \tilde{f} : \tau, \overline{M}) \) and \( \text{methods}(T) = \overline{M}' \). From rule (RT-REPL) we have:

\[
\Sigma \vdash \tau : C' \quad \exists l[R], \quad C' <: l[R] \implies T < R \text{ OK}
\]

where \( \Sigma \vdash \mathcal{H} \) implies \( C' = C \), thus \( C <: l[R] \). To prove that \( \Sigma \vdash \mathcal{H}' \) we have to show that:

1. \( m\text{Sig}(\text{exclude}(\overline{M}, \text{names}(\overline{M}))) \cup \overline{M} \subseteq m\text{Sig}(C) \)
2. \( \forall \forall \text{ m } (\overline{V} \overline{x})\{ \text{return } e; \} \in \text{exclude}(\overline{M}, \text{names}(\overline{M})) \cup \overline{M}' \exists \overline{V}' \text{ such that this : } C, \overline{x} : \overline{V} \vdash e : \overline{V}' \text{ with } \overline{V}' <: \overline{V} \).

Point (1). By hypothesis we have \( m\text{Sig}(\overline{M}) \subseteq m\text{Sig}(C) \) we just have to show \( m\text{Sig}(\overline{M}') \subseteq m\text{Sig}(C) \). From rule (\text{T-OK}) and (T-TEBASIC) we have

\[
\vdash \text{trait } T \text{ is } \text{TE}' (\mu_1 \ldots \mu_p \vdash \rho > 0) \quad \forall i \in 1 \ldots p, \quad \mu_i = \xi : \{ F^{(i)} , \overline{\sigma}^{(i)} , \overline{U}^{(i)} \} \vdash \Delta^{(i)}
\]

\[
\text{R}_T \subseteq R \text{ which implies } m\text{Sig}(S) \supseteq (U_{i=1}^{p} \text{U}^{(i)})
\]

thus \( (U_{i=1}^{p} \xi(i)) = m\text{Sig}(\overline{M}') \subseteq m\text{Sig}(S) \).

Let

\[
\text{class } C \text{ implements } \text{I by } \text{TE}' \{ F, K \}
\]

\[
\overline{M}' = \text{methods}(\text{TE}')
\]

then from subtyping rule \( C <: l[R] \) we have that \( R \supseteq R_C \) which implies

\[
m\text{Sig}(\overline{M}') \supseteq m\text{Sig}(S \cup Z)
\]

Thus \( m\text{Sig}(C) = m\text{Sig}(\overline{M}') \supseteq m\text{Sig}(S \cup Z) \supseteq m\text{Sig}(S) \) which proves the result.

Point (2). By hypothesis we have \( \forall \forall \text{ m } (\overline{V} \overline{x})\{ \text{return } e; \} \in \overline{M}, \exists \overline{V}' \text{ such that this : } C, \overline{x} : \overline{V} \vdash e : \overline{V}' \text{ with } \overline{V}' <: \overline{V} \). By Lemma A.7 we have \( \forall \forall \text{ m } (\overline{V} \overline{x})\{ \text{return } e; \} \in \overline{M}, \exists \overline{V}' \text{ s. t. this : } C, \overline{x} : \overline{V} \vdash e : \overline{V}' \text{ with } \overline{V}' <: \overline{V} \) which proves the result. \( \Box \)

**A.2. Proof of Theorem 5.4**

**Lemma A.8.** Given the configuration \( e, \mathcal{H} \), such that \( \Sigma \vdash \mathcal{H} \) and \( \Sigma \vdash e : \pi \), then

1. If \( e = \tau.f \) then \( \mathcal{H}(t) = (C, \tilde{f} : \tau, \ldots, \overline{M}) \) for some \( C, \tilde{f} \) and \( \overline{M} \) such that \( f_i \in \tilde{f} \);
2. If \( e = 1.m(\overline{T}) \) then \( \mathcal{H}(t) = (C, \tilde{f} : \tau, \overline{M}) \) for some \( C, \tilde{f} \) and \( \overline{M} \) such that \( \text{U m } (\overline{U} \overline{x})\{ \text{return } e'; \} \in \text{exclude}(\text{methods}(C), \text{names}(\overline{M})) \cup \overline{M} \) and \( |\overline{x}| = |\overline{T}| \);
3. If \( e = \text{new } C(T) \) then \text{fields}(C) = \overline{U} \overline{f} \text{ for some } \overline{U}, \overline{f} \text{ and } |\overline{f}| = |\overline{T}| \)
4. If \( e = \tau \{ T \} \) then \( \mathcal{H}(t) = (C, \tilde{f} : \tau, \overline{M}) \) and \( \text{methods}(T) = \overline{M}' \) for some \( C, \tilde{f}, \tau, \overline{M} \) and \( \overline{M}' \).
Proof. 

1. Follows directly from well-formedness of heap. 

2. From rule (RT-INVK) we have that 
\[ \Sigma \vdash i : C' \quad \forall i \in 1..n, \quad \Sigma \vdash i' : C_i \quad C_i \vdash U_i \]
\[ U \land (U_1,..,U_n) = \text{choose}(mSig(C'),m) \]
where \( \Sigma \vdash \mathcal{H} \) implies \( C' = C \)

There are two cases: 
(a) \( U \land (U \land \langle \text{return } e' \rangle \}) \in \mathcal{M} \) then from \( \Sigma \vdash \mathcal{H} \) we have \( mSig(\mathcal{M}) \subseteq mSig(C) \) and thus \( U = U' \) and \( U = U' \).

(b) \( U \land (U \land \langle \text{return } e' \rangle \}) \in \text{methods}(C) \). Since \( C \) is well typed it easy to verify that such definition exists, 
i.e. \( \text{methods}(C) = \text{methods}(\text{TE}) \) for some \( \text{TE} \) if \textbf{class C implements I by TE} \{ \text{F, K} \}.

Note that \( \lvert x \rvert = \lvert \tau \rvert \) derives from rule (RT-INVK) since \( \lvert \tau \rvert = \lvert \mathcal{U} \}). 

3. Follows directly from rule (RT-NEW).

4. From rule (RT-REPL) and well formedness of the heap we have \( \mathcal{H}(1) = \langle C, \tau : \pi, \mathcal{M} \rangle \) for some \( C, \tau, \pi \) and \( \mathcal{M} \).

From rule (RT-REPL) we have \( \vdash \tau \vdash \mathcal{R} \quad \text{OK} \) then from rules (\vdash \text{-OK}) and (\mathcal{R}-\text{OK}) we have \( \text{methods}(\tau) = \mathcal{M}' \)
for some \( \mathcal{M}' \). □

Proof of Theorem 5.4 (Progress). The proof is by straightforward induction on the derivation of \( \Sigma \vdash e : \pi \) using Lemma A.8 in the basic cases. □