

Interactive Realizers

A new Approach to Program Extraction from Non-Constructive Proofs

Ugo de'Liguoro

Dipartimento di Informatica, Università di Torino

joint work with **Stefano Berardi**

Genova, October 21th 2010

A motivating example

Let f, g and h be total recursive functions, and consider:

$$\begin{cases} f(x) \leq f(g(x)) \\ f(x) \leq f(h(x)) \end{cases}$$

It is classically provable that the system always has a solution in \mathbb{N} , namely any m such that:

$$f(m) = \min \text{rng}(f).$$

Observe that:

- the number $\min \text{rng}(f)$ is not computable for all total recursive f : take e.g. $f_x(y) = r(x, y)$ where

$$r(x, y) = \begin{cases} 0 & \text{if } \varphi_x(x) \text{ converges within } y \text{ steps} \\ 1 & \text{else} \end{cases}$$

then to compute $\min \text{rng}(f_x)$ is the same as to decide the halt.

- however we can effectively find a solution of the original problem by minimalization:

$$\min x.f(x) \leq f(g(x)) \wedge f(x) \leq f(h(x))$$

thought this is a brute force algorithm

A better solution:

```
m := an arbitrary natural number
while  $f(m) > f(g(m)) \vee f(m) > f(h(m))$  do
  if  $f(m) > f(g(m))$  then  $m := g(m)$ 
  else // i.e. when  $f(m) > f(h(m))$ 
     $m := h(m)$ 
return m
```

The algorithm terminates: otherwise we would be able to construct the infinite descending chain of natural numbers

$$f(m_0) > f(m_1) > \cdots > f(m_i) > \cdots$$

with $m_i =$ the value of m after i executions of the while body.

The theories **PRA** and **PRA** + **EM**₁

- **PRA** is the quantifier free theory of primitive recursive arithmetic (see [Troelstra-Van Dalen], vol. 1)
- call \mathcal{L}_0 the first order predicate language with equality and without quantifiers of **PRA**
- call \mathcal{I}_0 the standard interpretation of \mathcal{L}_0 s.t. $\mathcal{I}_0 \models \mathbf{PRA}$

If $t, A \in \mathcal{L}_0$ are a term and a formula with free variables $\{x_1, \dots, x_k\}$ then

$$\llbracket t \rrbracket^{\mathcal{I}_0} : \mathbb{N}^k \rightarrow \mathbb{N} \quad \text{and} \quad \llbracket A \rrbracket^{\mathcal{I}_0} : \mathbb{N}^k \rightarrow \mathbb{B}$$

are a primitive recursive function and predicate respectively.

With A in the language of **PRA** consider:

$$(\mathbf{EM}_1) \quad \forall \vec{x}. \exists y A(\vec{x}, y) \vee \forall y \neg A(\vec{x}, y)$$

which is classically equivalent to to the skolemized version

$$\forall \vec{x}, y. A(\vec{x}, \varphi(\vec{x})) \vee \neg A(\vec{x}, y),$$

and to

$$\forall \vec{x}, y. A(\vec{x}, y) \rightarrow A(\vec{x}, \varphi(\vec{x})).$$

Let \mathcal{L}_1 be obtained from \mathcal{L}_0 by adding the symbols:

χ_P (a predicate) φ_P (a function) of arity k

for each predicate symbol $P \in \mathcal{L}_0$ of arity $k + 1$

Then **PRA** + **EM**₁ is obtained from **PRA** by adding the axioms:

$$(\chi) \quad P(\vec{x}, y) \rightarrow \chi_P(\vec{x})$$

$$(\varphi) \quad \chi_P(\vec{x}) \rightarrow P(\vec{x}, \varphi_P(\vec{x}))$$

for each (definition in **PRA** of) primitive recursive predicate P .

Extracting Programs from $\mathbf{PRA} + \mathbf{EM}_1$ Proofs

- A *program specification* is some formula $A(\vec{x}, y) \in \mathcal{L}_0$
- an *interactive program* is a term $t(\vec{x}) \in \mathcal{L}_1$
- a program $t(\vec{x})$ *provably satisfies the specification* $A(\vec{x}, y)$ if

$$\mathbf{PRA} + \mathbf{EM}_1 \vdash A(\vec{x}, t(\vec{x}))$$

Goal (naively): find a total recursive function $p(\vec{x})$ such that in some model $\mathcal{I} \models \mathbf{PRA} + \mathbf{EM}_1$ it is the case that

$$\forall \vec{m} \in \mathbb{N} \quad p(\vec{m}) = \llbracket t(\vec{m}) \rrbracket^{\mathcal{I}}$$

Problem

There exist terms t and formulas A of \mathcal{L}_1 whose interpretations $\llbracket t \rrbracket^{\mathcal{I}}$ and $\llbracket A \rrbracket^{\mathcal{I}}$ aren't computable in any model \mathcal{I} of **PRA** + **EM**₁

Goal: find a total recursive function $p(\vec{x})$ such that:

$$\forall \vec{m} \in \mathbb{N} \exists \mathcal{I} \supseteq \mathcal{I}_0. \mathcal{I} \models \forall \vec{x}. A(\vec{x}, t(\vec{x})) \quad \& \quad p(\vec{m}) = \llbracket t(\vec{m}) \rrbracket^{\mathcal{I}}$$

where observe the exchange of quantifiers w.r.t. the previous formulation, and the fact that \mathcal{I} is a model of a single theorem, not of the whole theory **PRA** + **EM**₁.

A constructive interpretation of $\mathbf{PRA} + \mathbf{EM}_1$

Idea:

- we define a notion of (finite) approximation of a $\mathbf{PRA} + \mathbf{EM}_1$ model such that the interpretation map is continuous
- we interpret non constructive proofs of $\mathbf{PRA} + \mathbf{EM}_1$ as strategies sending any possible value of the parameters into some finite approximation s_0 of a $\mathbf{PRA} + \mathbf{EM}_1$ model
- for any possible values of the parameters the concluding formula of the proof is true in any interpretation \mathcal{I} extending the approximation s_0 associated to the parameters

Facts and States of Knowledge

- *fact*: any atomic closed formula $P(\vec{m}, n) \in \mathcal{L}_0$ such that

$$\llbracket P(\vec{m}, n) \rrbracket^{\mathcal{I}_0} = \text{true}$$

- *consistency*: the relation among atomic closed formulas of \mathcal{L}_0 :

$$P(\vec{m}, n) \sim Q(\vec{m}', n') \Leftrightarrow [P \equiv Q \ \& \ \vec{m} = \vec{m}' \Rightarrow n = n']$$

where \equiv is syntactical identity

- *state*: a finite consistent set of facts

$$s = \{P_1(\vec{m}_1, n_1), \dots, P_k(\vec{m}_k, n_k)\}$$

we name \mathbb{S} the set of states

For any (possibly infinite) consistent set of facts S define:

$$\llbracket \chi_P \rrbracket(\vec{m}, S) = \text{true} \Leftrightarrow \exists n \in \mathbb{N}. P(\vec{m}, n) \in S$$

and

$$\llbracket \varphi_P \rrbracket(\vec{m}, S) = \begin{cases} n & \text{if } P(\vec{m}, n) \in S \text{ for some } n \\ 0 & \text{otherwise.} \end{cases}$$

Prop. Any maximal consistent set of facts S determines an interpretation $\mathcal{I}_S \supseteq \mathcal{I}_0$ of \mathcal{L}_1 by putting:

$$\llbracket \chi_P(\vec{m}) \rrbracket^{\mathcal{I}_S} = \llbracket \chi_P \rrbracket(\vec{m}, S) \quad \text{and} \quad \llbracket \varphi_P(\vec{m}) \rrbracket^{\mathcal{I}_S} = \llbracket \varphi_P \rrbracket(\vec{m}, S)$$

which is a model of $\mathbf{PRA} + \mathbf{EM}_1$. Viceversa any model $\mathcal{I} \supseteq \mathcal{I}_0$ determines the maximal consistent set of facts:

$$S_{\mathcal{I}} = \{P(\vec{m}, n) \mid \llbracket P(\vec{m}, n) \rrbracket^{\mathcal{I}} = \text{true} \wedge \llbracket \varphi_P(\vec{m}) \rrbracket^{\mathcal{I}} = n\}$$

The structure

$$(\mathbb{S}, \sqsubseteq, \uparrow, \sqcup, \perp)$$

is an effectively presented partial order with infimum and compatible finite sups, that is:

- ① \mathbb{S} is a decidable set
- ② $s \sqsubseteq s' \Leftrightarrow s \subseteq s'$ is a computable partial order
- ③ $s \uparrow s' \Leftrightarrow \exists s''. s \sqsubseteq s'' \sqsupseteq s'$ is decidable
- ④ $s \sqcup s' = s \cup s'$ if $s \uparrow s'$, undefined otherwise, is computable
- ⑤ $\perp = \emptyset$

The proof of (1), (3) and (4) follows since to be a “fact” is decidable, and because of the syntactical nature of the relation \sim among facts, which is decidable.

- A maximal consistent set of facts S can be viewed as the union of a (suitable) ω -chain of states:

$$s_0 \sqsubseteq s_1 \sqsubseteq \cdots \sqsubseteq s_j \sqsubseteq \cdots$$

and this can be done in many ways

- the interpretation $\llbracket E \rrbracket^{\mathcal{I}^s}$ of any closed $E \equiv t, A$ only depends on a finite subset of S , namely on a state s_i for suitably large index i
- both $\llbracket \chi_P \rrbracket(\vec{m}, s)$ and $\llbracket \varphi_P \rrbracket(\vec{m}, s)$ are computable for finite s (a state)

The Approximated Interpretation of \mathcal{L}_1

We interpret (closed) terms into $\mathbb{N}^{\mathbb{S}}$ (i.e. objects of type $\mathbb{S} \rightarrow \mathbb{N}$), and formulas into $\mathbb{B}^{\mathbb{S}}$ (of type $\mathbb{S} \rightarrow \mathbb{B}$). In general for $\xi : \text{Var} \rightarrow \mathbb{N}^{\mathbb{S}}$:

$$\llbracket x \rrbracket_{\xi}^{\mathbb{S}} = \xi(x)$$

$$\llbracket n \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. n$$

$$\llbracket f(t_1, \dots, t_n) \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. f(\llbracket t_1 \rrbracket_{\xi}^{\mathbb{S}}(s), \dots, \llbracket t_n \rrbracket_{\xi}^{\mathbb{S}}(s))$$

$$\llbracket \varphi_P(t_1, \dots, t_n) \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. \llbracket \varphi_P \rrbracket(\llbracket t_1 \rrbracket_{\xi}^{\mathbb{S}}(s), \dots, \llbracket t_n \rrbracket_{\xi}^{\mathbb{S}}(s), s)$$

$$\llbracket P(t_1, \dots, t_n) \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. P(\llbracket t_1 \rrbracket_{\xi}^{\mathbb{S}}(s), \dots, \llbracket t_n \rrbracket_{\xi}^{\mathbb{S}}(s))$$

$$\llbracket \chi_P(t_1, \dots, t_n) \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. \llbracket \chi_P \rrbracket(\llbracket t_1 \rrbracket_{\xi}^{\mathbb{S}}(s), \dots, \llbracket t_n \rrbracket_{\xi}^{\mathbb{S}}(s), s)$$

$$\llbracket (A \wedge B) \rrbracket_{\xi}^{\mathbb{S}} = \lambda s. \llbracket A \rrbracket_{\xi}^{\mathbb{S}}(s) \wedge \llbracket B \rrbracket_{\xi}^{\mathbb{S}}(s)$$

...

A Submonad of the State Monad

The following is a Kleisli triple:

$$\begin{aligned} \mathcal{S}X &= X^{\mathbb{S}} \\ \eta_X(x) &= \lambda s. x \quad (\text{written } \lambda_. x) \\ f^*(\alpha) &= \lambda s. f(\alpha(s), s) \end{aligned}$$

where $f : X \rightarrow \mathcal{S}Y$, $\alpha \in X^{\mathbb{S}}$ and $f^* : \mathcal{S}X \rightarrow \mathcal{S}Y$.

$\mathcal{S} : \mathbf{Set} \rightarrow \mathbf{Set}$ is a functor whose arrow part is:

$$\mathcal{S}f = (\eta_Y \circ f) = f \circ _$$

The monad multiplication is $\mu_X = \text{Id}_{\mathcal{S}X}^*$ that is:

$$\mu_X(\delta, s) = \delta(s, s), \quad \text{for any } \delta \in \mathcal{S}^2X = (X^{\mathbb{S}})^{\mathbb{S}} \text{ and } s \in \mathbb{S}$$

$(\mathcal{S}, \eta, \mu, t)$ is a strong monad with (unique) tensorial strength:

$$t_{X,Y}^{\mathcal{S}} : X \times \mathcal{S}Y \rightarrow \mathcal{S}(X \times Y)$$

defined as

$$t_{X,Y}^{\mathcal{S}}(x, \alpha) = \lambda s. (x, \alpha(s))$$

Taking as in [Moggi 91]

$$\psi_{X,Y} := (t_{X,Y} \circ c_{\mathcal{S}Y,X})^* \circ t_{\mathcal{S}Y,X} \circ c_{\mathcal{S}X,\mathcal{S}Y}$$

where $c_{X,Y} : X \times Y \rightarrow Y \times X$ is the exchange iso, we get

$$\psi_{X,Y}(\alpha, \beta) = \langle \alpha, \beta \rangle = \lambda s : \mathbb{S}. (\alpha(s), \beta(s)),$$

which has inverse $\gamma \mapsto (\pi_1 \circ \gamma, \pi_2 \circ \gamma)$ determining the iso $\mathcal{S}X \times \mathcal{S}Y \simeq \mathcal{S}(X \times Y)$

The Category of Global Functions

Let $\mathbf{Set}_{\mathcal{S}}$ be the Kleisli category of \mathcal{S} ; define the isomorphic category $\mathbf{Set}_{\mathcal{S}}^*$ by $|\mathbf{Set}_{\mathcal{S}}^*| = |\mathbf{Set}_{\mathcal{S}}| = |\mathbf{Set}|$ and

$$\mathbf{Set}_{\mathcal{S}}^*(X, Y) = \{f^* \mid f \in \mathbf{Set}_{\mathcal{S}}(X, Y)\} = \{f^* \mid f : X \rightarrow \mathcal{S}Y \in \mathbf{Set}\}$$

Def. A function $g : \mathcal{S}X \rightarrow \mathcal{S}Y$ is *global* iff

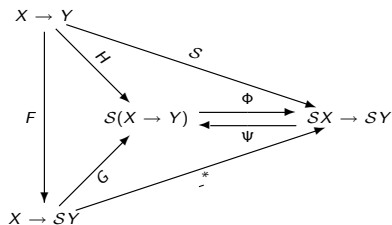
$$\forall \alpha \in \mathcal{S}X \forall s \in \mathbb{S}. g(\alpha, s) = g(\lambda_{-}. \alpha(s), s)$$

Global functions are a subset of $\mathcal{S}X \rightarrow \mathcal{S}Y$: let $s, s' \in \mathbb{S}$ be distinct, $h : \mathbb{S} \rightarrow \mathbb{S}$ s.t. $h(s) = s'$ and $\alpha \in \mathcal{S}$ s.t. $\alpha(s) \neq \alpha(s')$ then:

$$(\lambda \beta. \beta \circ h)(\alpha, s) = \alpha(s') \neq \alpha(s) = (\lambda \beta. \beta \circ h)(\lambda_{-}. \alpha(s), s)$$

Lemma Global functions in $\mathcal{S}X \rightarrow \mathcal{S}Y$ are exactly morphisms in $\mathbf{Set}_{\mathcal{S}}^*(X, Y)$

The following diagram commutes, and $\Psi \circ \Phi$ is a retraction:



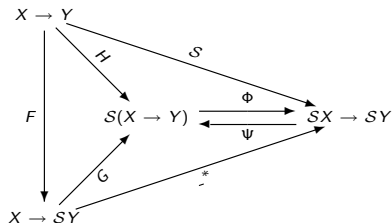
$$\Phi : S(X \rightarrow Y) \rightarrow (SX \rightarrow SY) \quad \Phi(f)(\alpha, s) := f(s)(\alpha(s))$$

$$\Psi : (SX \rightarrow SY) \rightarrow S(X \rightarrow Y) \quad \Psi(g)(s, x) := g(\lambda_{-}.x, s)$$

$$F : (X \rightarrow Y) \rightarrow (X \rightarrow SY) \quad \text{where} \quad F(f) := \lambda x \in X \lambda_{-} \in \mathbb{S}.f(x)$$

$$G : (X \rightarrow SY) \rightarrow S(X \rightarrow Y) \quad \text{where} \quad G(g) := \lambda s \in \mathbb{S} \lambda x \in X.g(x, s)$$

$$H : (X \rightarrow Y) \rightarrow S(X \rightarrow Y) \quad \text{where} \quad H(f) := \lambda_{-} \in \mathbb{S}.f$$



The image of Φ is exactly the set of global functions: if $f : X \rightarrow SY$ then for all $\alpha \in SX$ and $s \in \mathbb{S}$:

$$f^*(\alpha, s) = f(\alpha(s), s) = f((\lambda _ . \alpha(s))(s), s) = f^*(\lambda _ . \alpha(s), s),$$

hence f^* is global. Viceversa if g is global then $g = \Phi(h) = \lambda \alpha \in SX \ s \in \mathbb{S}. h(s)(\alpha(s))$, for some $h : \mathbb{S} \rightarrow (X \rightarrow Y)$. Set $f(x, s) = h(s, x)$, so that $f : X \rightarrow SY$; then:

$$g = \lambda \alpha \in SX \ s \in \mathbb{S}. f(\alpha(s), s) = f^*.$$

\mathbf{Set}_S^* is cartesian: given $f : Z \rightarrow SX$ and $g : Z \rightarrow SY$ the arrow

$$\langle f, g \rangle^* : SZ \rightarrow S(X \times Y)$$

is the unique one such that the following commutes:

$$\begin{array}{ccccc}
 & & Z^S & & \\
 & \swarrow f^* & \downarrow \langle f, g \rangle^* & \searrow g^* & \\
 X^S & \xleftarrow{\pi_1 \circ -} & (X \times Y)^S & \xrightarrow{\pi_2 \circ -} & Y^S
 \end{array}$$

where $\pi_i \circ - = S\pi_i$ ($i = 1, 2$). Then we get

$$\langle f, g \rangle^* = \langle f^*, g^* \rangle$$

up to the iso $SX \times SY \simeq S(X \times Y)$.

Def. $g : \mathcal{S}X_1 \times \cdots \times \mathcal{S}X_k \rightarrow \mathcal{S}Y$ is *k-global* if for all $\alpha_1, \dots, \alpha_k, s$:

$$g(\alpha_1, \dots, \alpha_k, s) = g(\lambda_{\cdot} \alpha_1(s), \dots, (\lambda_{\cdot} \alpha_k(s), s))$$

Any *k-global* g uniquely factors through

$$\psi_{X_1, \dots, X_k} : \mathcal{S}X_1 \times \cdots \times \mathcal{S}X_k \rightarrow \mathcal{S}(X_1 \times \cdots \times X_k)$$

by

$$\mathcal{S}X_1 \times \cdots \times \mathcal{S}X_k \xrightarrow{\psi_{X_1, \dots, X_k}} \mathcal{S}(X_1 \times \cdots \times X_k) \xrightarrow{\hat{g}} \mathcal{S}Y$$

where $\hat{g}(\gamma) = g(\pi_1 \circ \gamma, \dots, \pi_k \circ \gamma)$.

It follows that g is *k-global* if and only if $\hat{g} = g \circ \psi^{-1}$ is global.

Individuals

Def. Let $\sigma : \mathbb{N} \rightarrow \mathbb{S}$ be an ω -chain over \mathbb{S} , that is

$$\sigma(0) \sqsubseteq \sigma(1) \sqsubseteq \cdots \sqsubseteq \sigma(i) \sqsubseteq \cdots$$

and $\alpha \in \mathcal{S}X = X^{\mathbb{S}}$; then $\alpha \circ \sigma : \mathbb{N} \rightarrow X$ is *convergent* and it has a *limit point* $\lim(\alpha \circ \sigma) = x$ if

$$\exists i \forall j. (\alpha \circ \sigma)(i) = (\alpha \circ \sigma)(i + j) = x.$$

The mapping α is *strongly convergent* if for all ω -chain σ , $\alpha \circ \sigma$ is convergent.

We call *individual* of X a strongly convergent $\alpha \in \mathcal{S}X$, and denote by $I(X)$ the set of individuals of X .

Density Theorem

The behaviour of a global function is completely determined by its values on constant individuals. Let $f, g : SX \rightarrow SY$ be global:

- ① if $f(\lambda_{\cdot}x) = g(\lambda_{\cdot}x)$ for all $x \in X$ then $f = g$
- ② if $f(\lambda_{\cdot}x) \in I(Y)$ for all $x \in X$ then $f(\alpha) \in I(Y)$ for all $\alpha \in I(X)$

Part (1) follows by the fact that if f, g are global then $f = \bar{f}^*$ for some $\bar{f} : X \rightarrow SY$ (and similarly for g) and \bar{f}^* is the unique arrow s.t. the following commutes:

$$\begin{array}{ccc}
 X & & \\
 \eta \downarrow & \searrow \bar{f} & \\
 SX & \xrightarrow{f = \bar{f}^*} & SY
 \end{array}$$

Now recall that $\eta(x) = \lambda_{\cdot}x$

The Category of Strongly Global Functions

Def. A global $f : SX \rightarrow SY$ is *strongly global* if

$$\forall x \in X. f(\lambda_{..x}) \in I(Y)$$

Lemma If $f : SX \rightarrow SY$ and $g : SY \rightarrow SZ$ are strongly global then $g \circ f$ is strongly global. Moreover Id_{SX} is strongly global.

Proof. $f = \bar{f}^*$ and $g = \bar{g}^*$ therefore their composition is global:

$$\bar{g}^* \circ \bar{f}^* = (\bar{g}^* \circ \bar{f})^*$$

by Kleisli composition and because global functions are exactly those of the form h^* for some h

$\beta = f(\lambda_{..x}) \in I(Y)$, hence $g(\beta) \in I(Z)$ by part (2) of Density Thm, and we conclude $(g \circ f)(\lambda_{..x}) \in I(Z)$

Def. A global $f : SX \rightarrow SY$ is *strongly global* if

$$\forall x \in X. f(\lambda_{-.}x) \in I(Y)$$

By the lemma it exists a *category of strongly global functions* \mathcal{G} :

- $|\mathcal{G}| = |\mathbf{Set}|$ (morally the object X is $I(X)$)
- $\mathcal{G}(X, Y) = \{f \in \mathbf{Set}_S^* \mid f \text{ is strongly global}\}$

which is a subcategory of \mathbf{Set}_S^* (hence of \mathbf{Set}_S). Moreover \mathcal{G} is cartesian and product and projections coincide with those in \mathbf{Set}_S^* :

$$\pi_i \circ (\lambda_{-.}(x_1, x_2)) = \lambda_{-.}x_i$$

and if f, g are strongly global $\alpha = f(\lambda_{-.}z) \in I(X)$, $\beta = g(\lambda_{-.}z) \in I(X)$

$$\langle f, g \rangle (\lambda_{-.}z) = \langle \alpha, \beta \rangle \in I(X \times Y)$$

Approximated Interpretation Revised

For $t, A \in \mathcal{L}_1$ the interpretations $\llbracket t \rrbracket^{\mathbb{S}}$ and $\llbracket A \rrbracket^{\mathbb{S}}$ are arrows of \mathcal{G} :

$$I(\mathbb{N}) \times \cdots \times I(\mathbb{N}) \xrightarrow{\llbracket t \rrbracket^{\mathbb{S}}} I(\mathbb{N})$$

$$I(\mathbb{N}) \times \cdots \times I(\mathbb{N}) \xrightarrow{\llbracket A \rrbracket^{\mathbb{S}}} I(\mathbb{B})$$

e.g. if P is binary

$$\llbracket \varphi_P \rrbracket^{\mathbb{S}} = \llbracket \varphi_P \rrbracket^* \quad \text{where} \quad \llbracket \varphi_P \rrbracket : \mathbb{N} \rightarrow \mathbb{N}^{\mathbb{S}}$$

and $\llbracket \varphi_P \rrbracket(n) \in I(\mathbb{N})$ for all n

Prop. If $t, A \in \mathcal{L}_0$ then both $\llbracket t \rrbracket^{\mathbb{S}}$ and $\llbracket A \rrbracket^{\mathbb{S}}$ are constant. In particular if $\text{PRA} + \text{EM}_1 \vdash A$ then $\llbracket A \rrbracket^{\mathbb{S}}$ is constantly true.

Interactive Realizers

Def. An *interactive realizer* (shortly *realizer*) is a map $r \in \mathcal{S}(\mathbb{S}) = \mathbb{S}^{\mathbb{S}}$, such that:

- ① $r \in I(\mathbb{S})$ i.e. r is strongly convergent
- ② $r(s) \uparrow s$ for all $s \in \mathbb{S}$
- ③ $r(s) \cap s = \perp$ for all $s \in \mathbb{S}$

We call \mathbb{R} the set of realizers.

A state $s \in \mathbb{S}$ is a *prefix point* of $r \in \mathbb{R}$ if $r(s) \sqsubseteq s$; we set

$$\text{Prefix}(r) = \{s \in \mathbb{S} \mid r(s) \sqsubseteq s\}$$

Observe that if $r \in \mathbb{R}$ then by (3):

$$r(s) \sqsubseteq s \Leftrightarrow r(s) = \perp$$

so that $\lim(r \circ \sigma) = \perp$ for any ω -chain $\sigma : \mathbb{N} \rightarrow \mathbb{S}$.

Given $s \in \mathbb{S}$ define the ω -chain $\sigma : \mathbb{N} \rightarrow \mathbb{S}$ by:

$$\begin{aligned}\sigma(0) &= s \\ \sigma(i+1) &= \sigma(i) \sqcup r(\sigma(i))\end{aligned}$$

where $\sigma(i) \sqcup r(\sigma(i))$ exists since $r(\sigma(i)) \uparrow \sigma(i)$.

Since $r \in I(\mathbb{S})$ there exists $i_0 \in \mathbb{N}$ s.t. $r(\sigma(j)) = \perp$ for all $j \geq i_0$.

Choosing $s' = \sigma(i_0)$ we have:

$$s = \sigma(0) \sqsubseteq \sigma(i_0) = s' \in \text{Prefix}(r)$$

Prop. If $r \in \mathbb{R}$ then $\text{Prefix}(r)$ is cofinal in \mathbb{S}

Merging Realizers and a new Monad

A *merge* is a binary operation $\bullet : \mathbb{S} \times \mathbb{S} \rightarrow \mathbb{S}$ s.t.

- ① $(\mathbb{S}, \bullet, \perp)$ is a monoid
- ② if $s_1 \bullet s_2 = \perp$ then $s_1 = \perp = s_2$
- ③ $s_1 \bullet s_2 \subseteq s_1 \cup s_2$

Examples:

$$s_1 \bullet_0 s_2 = \begin{cases} s_1 & \text{if } s_1 \neq \perp, \\ s_2 & \text{otherwise.} \end{cases}$$

Let $\bar{s} = \{P(\vec{m}, n) \mid \exists n'. P(\vec{m}, n') \in s\}$:

$$s_1 \bullet_1 s_2 := s_1 \cup (s_2 \setminus \bar{s}_1)$$

For $X \subseteq \bigcup \mathbb{S}$ define $\widehat{X} := \{P(\vec{m}, n) \in X \mid \forall P(\vec{m}, n') \in X. n \leq n'\}$:

$$s_1 \bullet_2 s_2 := \widehat{s_1 \cup s_2}.$$

Define

$$\bullet^{\mathcal{S}} = \mathcal{S}(\bullet) \circ \psi_{\mathcal{S}, \mathcal{S}} : \mathcal{S}(\mathcal{S}) \times \mathcal{S}(\mathcal{S}) \rightarrow \mathcal{S}(\mathcal{S})$$

This is a 2-global function by construction, and the following is a monoid

$$(\mathcal{S}(\mathcal{S}), \bullet^{\mathcal{S}}, \lambda_{\perp}, \perp)$$

Note that $(\lambda_{\perp}.s) \bullet^{\mathcal{S}} (\lambda_{\perp}.s') = \lambda_{\perp}.(s \bullet s')$ so $\bullet^{\mathcal{S}}$ is strongly global. We conclude that $(\mathcal{S}, \bullet^{\mathcal{S}}, \lambda_{\perp}, \perp)$ is a monoid in \mathcal{G} .

Lemma If $r, r' \in \mathbb{R}$ then

$$r \bullet^{\mathcal{S}} r' \in \mathbb{R} \quad \text{and} \quad \text{Prefix}(r \bullet^{\mathcal{S}} r') = \text{Prefix}(r) \cap \text{Prefix}(r')$$

(Here we use the fact that $s \bullet s' = \perp$ implies that $s = \perp = s'$)

Therefore $(\mathbb{R}, \bullet^{\mathcal{S}}, \lambda_{\perp}, \perp)$ is a submonoid of $(\mathcal{S}(\mathcal{S}), \bullet^{\mathcal{S}}, \lambda_{\perp}, \perp)$

Monads of Realizers

Let $M = (\mathbb{S}, \bullet^{\mathbb{S}}, \lambda_{-}, \perp)$ (recall that \mathbb{S} is $I(\mathbb{S}) \subseteq \mathbb{S}^{\mathbb{S}}$ in \mathcal{G} and we are interested into $\mathbb{R} \subseteq I(\mathbb{S})$) be the monoid determined by the merge \bullet , and define the functor $\mathcal{R} : \mathcal{G} \rightarrow \mathcal{G}$:

$$\mathcal{R}(X) = M \times X \quad \mathcal{R}(g)(r, \alpha) = (r, g(\alpha))$$

where recall that $g \in \mathcal{G}(X, Y)$ is a strongly global function $g : I(X) \rightarrow I(Y)$, so $\alpha \in I(X) \subseteq X^{\mathbb{S}}$ and $g(\alpha) \in I(Y)$.

\mathcal{R} is a monad over \mathcal{G} , that we say a *realizer monad*, with unit

$$\begin{aligned} \eta_X^{\mathcal{R}} : X &\rightarrow \mathcal{R}(X) = M \times X \\ \alpha &\mapsto (\lambda_{-}.\perp\alpha) \end{aligned}$$

and multiplication

$$\begin{aligned} \mu_X^{\mathcal{R}} : \mathcal{R}^2(X) = M \times M \times X &\rightarrow \mathcal{R}(X) = M \times X \\ (r, r', \alpha) &\mapsto (r \bullet^{\mathbb{S}} r', \alpha) \end{aligned}$$

We recover the Kleisli $(-)^{*R}$ extension of \mathcal{R}

$$\begin{array}{ccc}
 X & & \\
 \eta_X^{\mathcal{R}} \downarrow & \searrow g & \\
 M \times X & \xrightarrow{g^{*R}} & M \times Y
 \end{array}$$

where supposing $g(\alpha) = (r', \beta)$ we have:

$$g^{*R}(r, \alpha) = (\mu_Y^{\mathcal{R}} \circ \mathcal{R}(g))(r, \alpha) = \mu_Y^{\mathcal{R}}(r, g(\alpha)) = (r \bullet^S r', \beta)$$

Interactive Forcing

Let X be any set, and $Y = \{Y_s \mid s \in \mathbb{S}\}$ with $Y_s \subseteq X$ for all s ; let $r \in \mathbb{R}$ and $\alpha \in I(X)$.

Def. r *interactively forces* α into Y is defined by

$$r \Vdash \alpha : Y \quad \Leftrightarrow \quad \forall s \in \mathbb{S} [s \in \text{Prefix}(r) \Rightarrow \alpha(s) \in Y_s]$$

$\text{ext}(A) = \{\text{ext}(A)_s \mid s \in \mathbb{S}\}$ where:

$$\text{ext}(A)_s = \{\vec{m} \mid \text{FV}(A) \subseteq \vec{x} \ \& \ |\vec{x}| = |\vec{m}| \ \& \ \llbracket A \rrbracket_{[\lambda \dots m / \vec{x}]}^{\mathbb{S}}(s) = \text{true}\}.$$

For $\vec{\alpha} = \alpha_1, \dots, \alpha_k$ we eventually set:

$$r \Vdash \vec{\alpha} : A(\vec{x}) \quad \Leftrightarrow \quad r \Vdash \langle \alpha_1, \dots, \alpha_k \rangle : \text{ext}(A)$$

The Interactive Realizability Theorem

Thm. If $\mathbf{PRA} + \mathbf{EM}_1 \vdash A(\vec{x})$ then there exists a strongly global $R : I(\mathbb{N}) \times \cdots \times I(\mathbb{N}) \rightarrow \mathbb{R}$ such that:

$$\forall \vec{\alpha} \in I(\mathbb{N}). \quad R(\vec{\alpha}) \Vdash \vec{\alpha} : A(\vec{x})$$

Moreover R , which is recursive (definable in Gödel system \mathbf{T}), is patterned after the proof of $A(\vec{x})$.

From the proof:

(χ)-axiom:

$$r_P(\vec{m}, n, s) = \begin{cases} \{P(\vec{m}, n)\} & \text{if } \llbracket P(\vec{m}, n) \rrbracket^{\mathcal{I}_0} = \text{true and } \forall n'. P(\vec{m}, n') \notin s \\ \perp & \text{else.} \end{cases}$$

Then setting $r_P^S = r_P^* \circ \psi_{\mathbb{N}^{k+1}}$, for any $\vec{\alpha}, \beta \in I(\mathbb{N})$ we have:

$$r_P^S(\vec{\alpha}, \beta) \Vdash \vec{\alpha}, \beta : P(\vec{x}, y) \rightarrow \chi_P(\vec{x})$$

Modus Ponens:

$$\frac{r \Vdash \vec{\alpha} : A \quad r' \Vdash \vec{\alpha} : A \rightarrow B}{r \bullet^S r' \Vdash \vec{\alpha} : B}$$