

Characterizing convergent terms in object calculi via intersection types

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Toward logic semantics of objects

- logic semantics amounts to type characterization of relevant computational properties;
- it is a tool for the study of syntactical properties (normalization, strong normalization, standardization);
- it can be used to achieve a concrete description of denotational models (filter models, domain logic);
- it could be a tool to analyze notions of subtyping (like matching) which otherwise have only a syntactical definition (this for the future).

The type-free ζ -calculus [AC96]

$$a, b ::= x \mid [l_i = \zeta(x_i)b_i]^{i \in I} \mid a.l \mid a.l \Leftarrow \zeta(x)b$$

Define the one-step reduction relation by

$$\text{i) } [l_i = \zeta(x_i)b_i]^{i \in I}.l_j \rightarrow_{\zeta} b_j \{ [l_i = \zeta(x_i)b_i]^{i \in I} / x_j \}$$

$$\text{ii) } [l_i = \zeta(x_i)a]^{i \in I}.l_j \Leftarrow \zeta(x)b \rightarrow_{\zeta} [l_i = \zeta(x_i)a]^{i \in I \setminus \{j\}}.l_j = \zeta(x)b$$

$$\text{iii) } a \rightarrow_{\zeta} a' \Rightarrow a.l \rightarrow_{\zeta} a'.l$$

$$\text{iv) } a \rightarrow_{\zeta} a' \Rightarrow a.l \Leftarrow \zeta(x)b \rightarrow_{\zeta} a'.l \Leftarrow \zeta(x)b$$

Defining values as $v ::= [l_i = \zeta(x_i)b_i]^{i \in I}$ we have

$$a \downarrow v \Leftrightarrow a \xrightarrow{*}_{\zeta} v$$

Remark: \rightarrow_{ζ} is weaker than one-step reduction in [AC96]

Existing type systems in object calculi do not catch termination

In Abadi and Cardelli “Theory of Objects”, for any type A , the diverging term:

$$[1 = \zeta(x:[1:A])x.1].1$$

has type A (so any type has a fully undefined inhabitant).

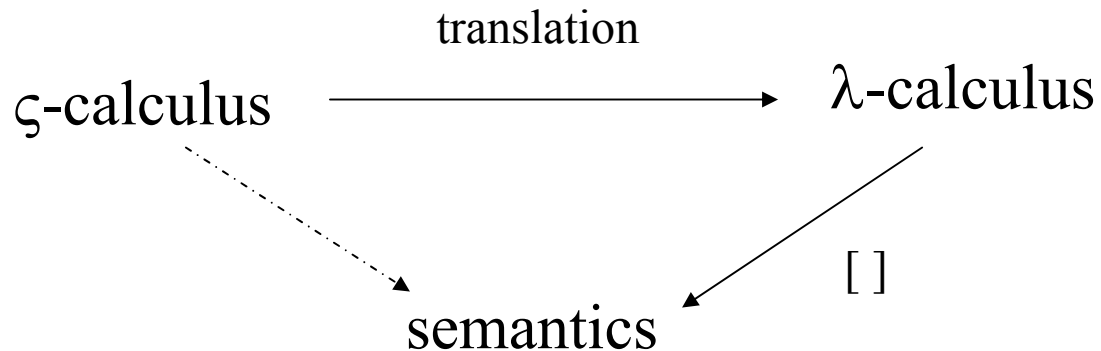
In terms of type assignment systems this can be restated as:

$$[1 = \zeta(x)x.1].1 \text{ has any type.}$$

Remark: this is not a criticism, as the same holds for PCF (e.g. `fix x.x`) or Pascal.

The present approach

- We consider a type-free λ -calculus and an interpretation of (type-free) ζ -calculus respecting and preserving convergency;
- we then provide a characterization of convergent λ -terms via an intersection type assignment system.



Λ_R : a λ -calculus with records

$M, N ::= x \mid \lambda x.M \mid MN \mid \langle l_i = M_i^{i \in I} \rangle \mid M \cdot l \mid M \cdot l := N$

(β) $(\lambda x.M)N \rightarrow M[N/x]$

(v) $M \rightarrow M' \Rightarrow MN \rightarrow M'N$

(R1) $\langle l_i = M_i^{i \in I} \rangle \cdot l_j \rightarrow M_j$, if $j \in I$

(R2) $M \rightarrow M' \Rightarrow M \cdot l \rightarrow M' \cdot l$

(R3) $\langle l_i = M_i^{i \in I} \rangle \cdot l_j := N \rightarrow \langle l_i = M_i^{i \in I \setminus \{j\}}, l_j = N \rangle$, if $j \in I$

(R4) $M \rightarrow M' \Rightarrow M \cdot l := N \rightarrow M' \cdot l := N$

record

selection

update

The self-application interpretation

Define (after Kamin 1988 and Abadi Cardelli 1996) a map:

$$[\]^S : \zeta\text{-terms} \rightarrow \Lambda_R$$

$$[x]^S = x$$

$$[[l_i = \zeta(x_i)b_i \text{ } i \in I]]^S = \langle l_i = \lambda x_i . [b_i]^S \text{ } i \in I \rangle$$

$$[a.l]^S = ([a]^S \cdot l) [a]^S$$

$$[a.l \leftarrow \zeta(x)b]^S = [a]^S \cdot l := \lambda x . [b]^S$$

Convergency

Let $V ::= \lambda x.M \mid \langle l_i = M_i^{i \in I} \rangle$ be the definition of values in the λ -calculus with records; then the *convergency* predicate is defined by:

$$M \Downarrow \Leftrightarrow \exists V. M \xrightarrow{*} V$$

An irreducible term like $(\lambda x.x) \cdot l$ is a normal form but not a value (hence it “diverges”).

Theorem. For any ζ -term a it is the case that

$$a \downarrow \Leftrightarrow [a]^S \Downarrow.$$

Goal: give a characterization of the convergency predicate via some type assignment system.

Known results about λ -calculus

Some relevant computational properties of type free λ -terms are characterized via intersection type assignment systems.

E.g. in BCD system (with type inequalities and a subsumption rule):

- M is solvable (has hnf) iff $\Gamma \vdash M : \sigma \neq \omega$
- M is normalizable (has nf) iff $\Gamma \vdash M : \sigma$ and $\omega \notin \Gamma, \sigma$
- M is strongly normalizable iff $D: \Gamma \vdash M : \sigma, \omega \notin \Gamma, \sigma, D$

Similar results hold in system CDV_ω (called $D\Omega$ by Krivine), where no type inequalities are considered.

Intersection types for Λ_R

$$\sigma, \tau ::= \alpha \mid \omega \mid \sigma \rightarrow \tau \mid \sigma \wedge \tau \mid \langle l_i : \sigma_i \mid i \in I \rangle$$

To the standard intersection type rules we add rules for records:

(Rec)

$$\frac{\Gamma \vdash M_i : \sigma_i \quad \forall i \in I \supseteq J}{\Gamma \vdash \langle l_i = M_i \mid i \in I \rangle : \langle l_i : \sigma_i \mid i \in J \rangle}$$

(Sel)

$$\frac{\Gamma \vdash M : \langle l_i : \sigma_i \mid i \in I \rangle \quad j \in I}{\Gamma \vdash M \cdot l_j : \sigma_j}$$

(Upd)

$$\frac{\Gamma \vdash M : \langle l_i : \sigma_i \mid i \in I \rangle \quad j \in I \quad \Gamma \vdash N : \tau}{\Gamma \vdash M \cdot l_j := N : \langle l_i : \sigma_i \mid i \in I \setminus \{j\}, l_j : \tau \rangle}$$

Comments on (*Upd*) rule

Consider the following variant of (*Upd*), closer to the typing of overriding in the Object Calculus:

$$\begin{array}{c} (Upd') \\ \hline \Gamma \vdash M : \langle l_i : \sigma_i \quad i \in I \rangle \quad j \in I \quad \Gamma \vdash N : \sigma_j \\ \hline \Gamma \vdash M \cdot l_j := N : \langle l_i : \sigma_i \quad i \in I \rangle \end{array}$$

same type

In this way we lose type invariance under expansion:

$$\langle l = \Omega \rangle \cdot l := (\lambda x.x) \rightarrow \langle l = \lambda x.x \rangle$$

Now $\langle l = \lambda x.x \rangle : \langle l : \sigma \rightarrow \sigma \rangle$

but, using (*Upd'*) in place of (*Upd*), we have at best

$$\langle l = \Omega \rangle \cdot l := (\lambda x.x) : \langle l : \omega \rangle$$

Invariance under reduction

The main reason for using intersection types and ω ,

$$\begin{array}{c} (\wedge I) \\ \Gamma \vdash M : \sigma \quad \Gamma \vdash M : \tau \\ \hline \Gamma \vdash M : \sigma \wedge \tau \end{array} \qquad \begin{array}{c} (\omega) \\ \hline \Gamma \vdash M : \omega \end{array}$$

is type invariance under subject reduction and expansion:

Subject reduction and expansion theorem. In the type system with ω , intersection, arrow and record types:

- if $\Gamma \vdash M : \sigma$ and $M \rightarrow N$ then $\Gamma \vdash N : \sigma$
- if $\Gamma \vdash N : \sigma$ and $M \rightarrow N$ then $\Gamma \vdash M : \sigma$

Some typing examples

$$a = [l = \zeta(x)3, m = \zeta(x)x.l \Leftarrow \zeta(y)x.l+1] : [l:int, m:[]]$$

translates to

$$M = \langle l = \lambda x.3, m = \lambda x.x \cdot l := \lambda y.(x \cdot l)x+1 \rangle$$

which is typable by

$$\langle l : \omega \rightarrow int, m : \omega \rangle$$

which is close to the $\text{Ob}_{1<}$ type, but also by

$$\langle l : \alpha \rightarrow int, m : \sigma \wedge \alpha \rightarrow \sigma \rangle$$

where $\sigma = \langle l : \alpha \rightarrow int, m : \beta \rangle$ (α, β type variables), which does not contain ω , as expected being M a normal form.

Type interpretation

Types are interpreted as sets of closed terms. Let us define

$$\mathbf{F} = \{\lambda x.M \mid \lambda x.M \in \Lambda_R^0\} \text{ and}$$

$$\mathbf{R} = \{\langle l_i = M_i^{i \in I} \rangle \mid \langle l_i = M_i^{i \in I} \rangle \in \Lambda_R^0\}.$$

Then, given some interpretation \mathfrak{I} of type variables,

$$[\alpha]_{\mathfrak{I}} = \mathfrak{I}(\alpha) \quad [\omega]_{\mathfrak{I}} = \Lambda_R^0 \quad [\sigma \wedge \tau]_{\mathfrak{I}} = [\sigma]_{\mathfrak{I}} \cap [\tau]_{\mathfrak{I}}$$

$$[\sigma \rightarrow \tau]_{\mathfrak{I}} = \{M \in \Lambda_R^0 \mid \exists F \in \mathbf{F}. M \Downarrow F \text{ and } \forall N \in [\sigma]_{\mathfrak{I}}. FN \in [\tau]_{\mathfrak{I}}\}$$

$$[\langle l_i : \sigma_i^{i \in I} \rangle]_{\mathfrak{I}} = \{M \in \Lambda_R^0 \mid \exists R \in \mathbf{R}. M \Downarrow R \text{ and } \forall i \in I. R \cdot l_i \in [\sigma_i]_{\mathfrak{I}}\}$$

Type inclusion

Define:

$$\sigma \leq \tau \Leftrightarrow \forall \mathfrak{S}. [\sigma]_{\mathfrak{S}} \subseteq [\tau]_{\mathfrak{S}}$$

and $\sigma = \tau$ if $\sigma \leq \tau$ and $\sigma \geq \tau$; then:

- $I \supseteq J \Rightarrow \langle l_i : \sigma_i \text{ }^{i \in I} \rangle \leq \langle l_j : \sigma_j \text{ }^{j \in J} \rangle$ (sub width)
- $\forall i \in I. \sigma_i \leq \tau_i \Rightarrow \langle l_i : \sigma_i \text{ }^{i \in I} \rangle \leq \langle l_i : \tau_i \text{ }^{i \in I} \rangle$ (sub depth)
- $\langle l_i : \sigma_i \text{ }^{i \in I} \rangle = \Lambda_{i \in I} \langle l_i : \sigma_i \rangle$
- $\langle l : \sigma \rangle \wedge \langle l : \tau \rangle = \langle l : \sigma \wedge \tau \rangle$

Remark. There are *empty* types, e.g. $(\omega \rightarrow \omega) \wedge \langle l : \omega \rangle$.

The characterization theorem

If $\mathfrak{S}(\alpha)$ is closed under (closed) expansions for all α , then $[\sigma]_{\mathfrak{S}}$ is such for any σ : we say that \mathfrak{S} is *saturated*.

Soundness lemma. If \mathfrak{S} is saturated, $\vartheta: \text{Var} \rightarrow \Lambda_R^0$ a closed substitution s.t. $\vartheta(x) \in [\sigma]_{\mathfrak{S}}$ for all $x:\sigma \in \Gamma$, then

$$\Gamma \vdash M : \tau \Rightarrow M\vartheta \in [\tau]_{\mathfrak{S}}$$

Characterization theorem. For any $M \in \Lambda_R$:

- $M \Downarrow F$, for some $F \in \mathbf{F}$, iff $\Gamma \vdash M : \omega \rightarrow \omega$, for some Γ ;
- $M \Downarrow R$, for some $R \in \mathbf{R}$, iff $\Gamma \vdash M : \langle \rangle$, for some Γ .

In particular, for any closed ζ -term a :

$$a \downarrow \text{ iff } \vdash [a]^S : \langle \rangle.$$

Conclusions and further work

The present work suggests that, beside PER models and standard domain theoretic techniques like solving domain equations, there is a further way to build and study models of object calculi, namely via type assignment and domain logic: *filter models*.

This remained implicit since a key problem, which is under study, is a reasonable *interpretation of typed terms and equalities*, and a comparison between the (typed) theories one obtains and theories of known models as well as operational theories, like the bisimulation theory of objects by Gordon and Rees.

Further *applications* are expected, essentially extending program logic as it has been developed in the functional case, to object calculi.

Next steps

- Ignoring empty types and considering type inclusion, a filter model comes out, which is a solution of the domain equation

$$D = A + (L \rightarrow D) + (D \rightarrow D).$$

- Types from typed object calculi may be interpreted as PER over D : is there a “logical” characterization of them?
- Given type interpretation, also typed equations are interpreted, and models can be compared w.r.t. their theories. Interesting would be the study of the bisimulation theory by Gordon and Rees.